

# Performance Evaluation of Data Mining based Images by using Fuzzy, Mean, Median Trilateral Filter

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## ABSTRACT

In Digital Image Processing removing the noise from an images is a very important to get the excellent result. Different filtering techniques like Median Filter and Mean Filter is not effective oftentimes for filtering the digital images. The newest procedure in this paper has focused on the data mining methods to improve data mining based fuzzy filtering further by utilizing filter for mixed noises and adaptive manifolds and high-dimensional mean-median filter for salt and pepper noises for successfully removing the noise. The latest working in this paper is that the usage of Trilateral filter for filtering the images, it is especially uses when a Gaussian noise is created in the images. The performance is evaluated by applying, Peak Signal to noise ratio, Root mean square error, Normalized cross-co relation it shows encouraging results.

## Keywords

Digital Image Processing, Multiplicative Noisy Images, Trilateral Filter, Root Mean square error, Peak signal to noise ratio, Normalized cross-co relation, Data Mining.

## 1. INTRODUCTION

Digital image processing could be the usage of using formulations to execute photograph managing on digital images. As a subcategory in addition to issue linked to digital managing, digital image processing has a few benefits about analog influence processing. It permits a considerably higher choice of formulation to acquire applied towards understanding data and reduce problems. Data mining can be an interdisciplinary subfield of pc science. It could be the computational procedure for exploring styles in big information models concerning techniques at the junction of synthetic intelligence, equipment understanding, statics and repository systems.

The overall purpose of the data mining method is always to acquire data from the information collection and change it in to a clear design for more use. The connected phrases knowledge, data mining and knowledge snooping reference the utilization of information mining solutions to trial areas of a larger information collection which can be may possibly also little for trusted statistical inferences to be manufactured in regards to the validity of any designs discovered. Data Mining requires five frequent courses of tasks.

- Anomaly Recognition
- Association
- Clustering
- Classification
- Regression

## 2. NOISE

### 2.1 Gaussian Noise

Removing with larger common deviations suppresses sound, but additionally blurs the image. Gaussian noise is mathematical sound hiring a likelihood occurrence purpose (PDF) similar compared to that in the conventional writing, that's also called the Gaussian is submitting. In few different words, the values the way the noise usually considers are generally Gaussian-distributed.

### 2.2 Salt and pepper Noise

The Salt & Pepper noise is observed on images. It occurs as occurring bright and black pixels.

### 2.3 Multiplicative Noise (Speckle Noise)

Speckle is a granular' noise 'that inherently exists in and degrades the rank of the powerful radar, medical ultrasound and visible coherence tomography images. The truly amazing most of products, synthetic or usual, are very difficult on the product range of the wavelength.

## 3. FILTER

A fresh algorithm is presented that may remove behavioral instinct noise by corrupted pictures while conserving details. The algorithm will depend on fuzzy behavioral instinct detection along with fuzzy disturbance cancellation techniques.

### 3.1 Trilateral Filter

Trilateral filter offers tougher noise decrease and greater outlier rejection in large gradient parts and it decrease the edge-limited removing behavior of shock-forming PDE's by area obtaining with an easy min-max stacks. Trilateral filtration quickly also includes N-Dimensional signs ,however additionally it presents greater efficiency for most visible purposes including appearance-preserving distinction decrease issues for electronic images and denoising polygonal works

### 3.2 Mean Filter

The mean filtration is really an easy sliding-window spatial filtration that changes the guts price in the screen with the common (mean) of all of the pixel prices in the window.

### 3.3 Median Filter

The median filtration can be a sliding-window spatial filtration; nonetheless it changes the price in the screen with the median of all pixel prices in the window. When it comes to mean filtration, the kernel is normally square but could be any shape.

## 4. PROPOSED METHOD

This work mainly focuses on the denoising and edge-preservation of different images. Different denoising methods

have been proposed but there is some scope of improvement. Noise is any unwanted signal that often gets added to the images when an image is being acquired or transmitted. In this planned work there is a use of Trilateral Filter is to be used for removing and detecting the noises from images also use for edge-preservation.

The proposed method involves the working as follows:

**Step 1:** First of all take an input image.

**Step 2:** Evaluate the noise type using Fuzzy rules.

**Step 3:** If there is a Gaussian Noise type is create then apply the Trilateral Filter. If there is a salt and pepper noise is create then apply Adaptive Manifolds and High-Dimensional Mean-Median Filter. If there is a mixed noise is created then applies Fuzzy Filter.

**Step 4:** After apply the filters, noise free image is created.

**Step 5:** Apply border correction for edge preservation.

**Step 6:** All steps to be completed Final image is output.

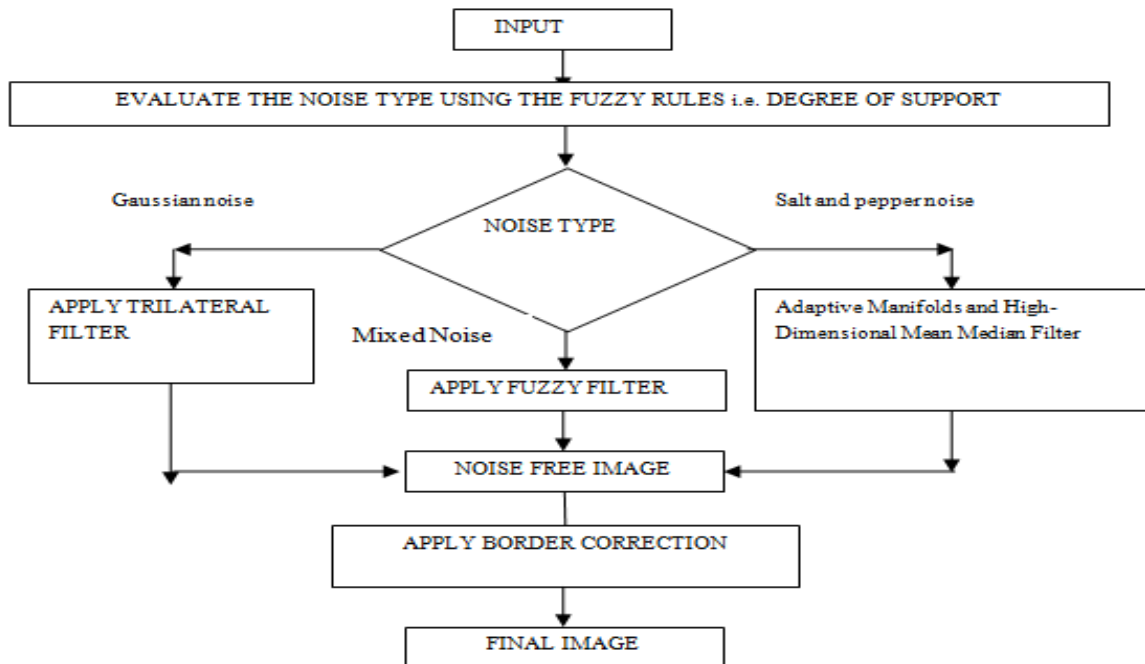


Fig 1: Flow chart of proposed algorithm

## 5. RESULTS AND DISCUSSION

For the fresh benefits planned algorithm, style and implementation has been conducted in MATLAB applying picture handling toolbox.

The figure 2 below shows three original input images of without the addition of noise. The noise create in the image usually disturbs the quality of an image.



a) Pepper Image b) Lena Image c) Barbara Image

Fig 2: Original Images

The figure 3 below shows the images in which are addition of noise. These three images is corrupted by 50% noise density.



a) Pepper Image b) Lena Image c) Barbara Image

Fig 3: Noisy Images with 50% noise corrupted

The figure 4 below shows the output results of the existing method which is afflicted with noise. These images are achieved by applying Mean-Median Filter on the input image which is noisy.



a) Pepper Image b) Lena Image c) Barbara Image

Fig 4: Existing Result Images

The figure 5 shown below is the final stage of our proposed work in which the edge preservation and denoising results are

shown. In the last step of our proposed work, trilateral filter is applied after applying the Mean-Median filter. The result shows that the proposed work gives best results than the existing methods



a) Pepper Image b) Lena Image c) Barbara Image

Fig 5: Proposed Output Images

## 6. PERFORMANCE EVALUATION

In that portion, an examination has been offered between the prevailing approach and the planned work with the foundation of contrast involving the three identified parameters. The relative examination can make certain that the planned approach increases results than the prevailing one.

### 6.1 Peak Signal to Noise Ratio

Peak square noise ratio is the ratio between the maximum possible value of the signal and the power of the corrupting noise. It is measured in decibels (db). It can be explained as:

$$10. \log_{10} \left( \frac{MAXI^2}{MSE} \right)$$

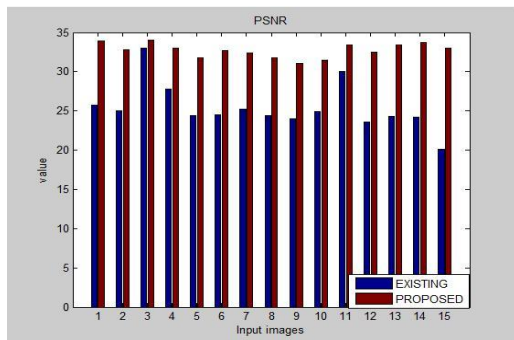


Fig 6: Graph for PSNR

In the above figure shows a plot between the existing technique shown in blue colour and the proposed technique shown in red colour. It clearly states that the proposed work shows good results as it shows increasing values for various images for PSNR.

The table 1 given below shows the values for both existing as well as proposed method. The values for PSNR should be increasing for each image for the proposed method, so it is clear from the comparison table that values for existing method are less and for proposed method are more.

Table1. Peak Signal to Noise Ratio

Image No.	Existing Results	Proposed Results
Image 1	25.7628	33.8962
Image 2	25.0314	32.8204
Image 3	32.9778	34.0044
Image 4	27.8267	33.0003

Image 5	24.4565	31.7419
Image 6	24.5328	32.6597
Image 7	25.2252	32.3509
Image 8	24.4383	31.7305
Image 9	23.9807	31.0339
Image 10	24.9254	31.5143
Image 11	30.0258	33.3816
Image 12	23.5914	32.5313
Image 13	24.2903	33.3650
Image 14	24.1789	33.7008
Image 15	20.1142	32.9808

### 6.2 Normalized cross-co relation

These measures measure the similarity between the two different images; hence, they are complementary to the difference based measures. As difference measure and correlation measures complement each other.

$$NCC = \frac{\sum \sum [I(U,V) * 0(U,V)]}{\sum \sum [I(U,V) * I(U,V)]}$$

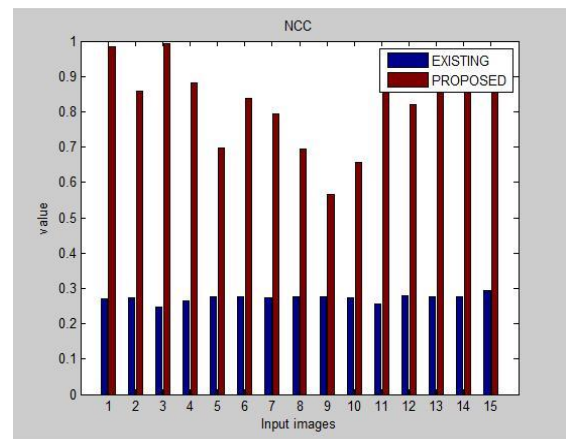


Fig 8: Graph for NCC

The above shown figure shows a comparison in the form of graph in which existing values are shown in blue colour and the values for proposed method are shown in red colour. As it is clear from the plot that proposed method shows improved results.

The table 2 given below shows the values for both existing as well as proposed method. The values for Normalized cross-co relation should be increasing for each image for the proposed method, so it is clear from the comparison table that values for existing method are less and for proposed method are more.

Table 2. Normalized cross-co relation

Image No.	Existing Results	Proposed results
Image 1	0.2707	0.9828
Image 2	0.2734	0.8578
Image 3	0.2466	0.9939

Image 4	0.2633	0.8808
Image 5	0.2755	0.6973
Image 6	0.2752	0.8364
Image 7	0.2726	0.7931
Image 8	0.2756	0.6954
Image 9	0.2773	0.5650
Image 10	0.2738	0.6575
Image 11	0.2559	0.9266
Image 12	0.2789	0.8188
Image 13	0.2762	0.9247
Image 14	0.2766	0.9622
Image 15	0.2931	0.8784

Image 2	14.2880	5.8280
Image 3	5.7233	5.0854
Image 4	10.3564	5.7085
Image 5	15.2657	6.5985
Image 6	15.1321	5.9369
Image 7	13.9727	6.1517
Image 8	15.2977	6.6072
Image 9	16.1252	7.1589
Image 10	14.4634	6.7737
Image 11	8.0399	5.4634
Image 12	16.8643	6.0252
Image 13	15.5605	5.4738
Image 14	15.7613	5.2662
Image 15	25.1669	5.7213

### 6.3 Root Mean Square Error

Root-mean-square error is a measure of the differences between values predicted by a model or an estimator and the values actually observed. It can be explained as:

$$RMSE = \sqrt{\frac{1}{KL} \sum_{U=1}^K \sum_{V=1}^L (G(U, V) - G'(U, V))^2}$$

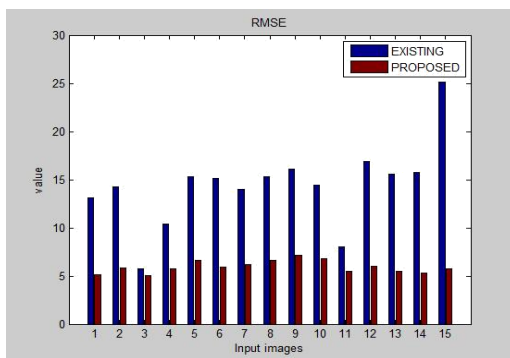


Fig 8: Graph for RMSE

Figure shows the analysis of RMSE of different images by showing the values of existing method shown in blue colour and the proposed method shown in red colour. The above graph states clearly that the proposed work shows better results than the existing work.

The values of Root Mean Square Error are given below in the comparison table 3. Table indicates the quantized examination of the Root Mean Square Error of various photographs by Existing value & planned values. It's specific from the plan that there surely is reduction in RMSE value of photos with the usage of planned strategy around different methods. That reduces shows development in the target quality of the image. This RMSE chart shows that the prices of planned algorithm is minimal than the prevailing algorithm which.

Table 3. Root Mean Square Error

Image No.	Existing Results	Proposed Results
Image 1	13.1341	5.1491

## 7. CONCLUSION

In this research work filtration methods based on image denoising techniques are given. Conventional filtering techniques like median filter and mean filter have not given the better results. This research work has focused on data mining based filtering techniques to check noise type and proposes a more rewarding trilateral filter it also improves median filter and mean filter. Different types of images such as grey scale or colored images are taken for experimental results. Trilateral filter, improved median filter, Mean filter gives better results as compare to the previous technique. These filters remove the noise at high noise density and preserve the edge of the grey scale as well as colored images.

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