ABSTRACT
Failure in Wireless Sensor Networks is common due to deployment of sensor nodes in harsh or hostile environment with limited power backup. Node failures could degrade the efficiency of sensor networks. Thus, failure detection and recovery techniques are very crucial for effective performance of nodes in Wireless Sensor Networks. In this paper we presented an improved DRFN technique by improving its failover mechanism. The failure handling scheme will be improved by using Artificial Bee Colony (ABC) based optimization technique. We analyze existing DRFN technique and compare it with the proposed technique on the basis of performance metrics such as occurrence of displacements and displacement overheads. Experimental results show that the proposed failure detection and recovery technique outperform over the available technique. The presented scheme is implemented and analyzed in 2013 version of MATLAB simulation tool.

Keywords
Artificial Bee Colony (ABC) based Optimization, Failure handling, Mobile nodes, Wireless sensor networks (WSN).

1. INTRODUCTION
In the last decade, Wireless Sensor Networks (WSNs) have emerged as a promising technology with growing interest in many applications areas such as space exploration, border and coastal security [2], [6],[15]. A wireless sensor network contains small sensor nodes that are placed over a large geographical area in order to monitor various physical phenomena like vibrations, temperature, seismic events, humidity and so on [3]. Sensor nodes are small in size, wirelessly communicating, where each node has a power battery, sensing range, communication ability and computation engine [19]. Base station is called sink node that are responsible for data collection from sensor nodes. Internet facility is used by base station for sending data to end users for further processing [13].

Sensor networks provide endless applications, such as monitoring environments, traffic movements and transportation, military observations, medical, and agronomic scientific etc. but at the same time provide forbidding challenges such as scarcity of energy [16]. Due to limited battery lifetime and low energy, sensors are in danger to different failures [18]. Faulty sensor nodes are one of the most important sources of faults [7]. The issue of failures handling in WSNs is very crucial, since nodes are often deployed in a harsh environment for example battlefield surveillance, fire detection, volcano or glacier monitoring and are prone to unexpected changes which may harm the normal operation of the WSNs[5],[8]. In this paper, we focus on improving DRFN technique by improving its failover scheme according to the principles of swarm intelligence by applying Artificial Bee Colony Based Optimization technique.

Swarm intelligence (SI) is a relatively novel field that generally refers to the study of the collective behavior of multi-component systems that coordinate using decentralized controls and self-organization [14]. In recent years, a new swarm intelligence-based optimization algorithm, called Artificial Bee Colony (ABC), has greatly attracted the attention of researchers [10]. Swarm intelligence contain a new member known as Artificial Bee Colony (ABC) technique. This technique has been applied to various problems such as in optimization of numerical problems, data clustering, wireless sensor network deployment and routing [12],[17]. In this paper Artificial Bee Colony technique is applied to find optimum path between sender & base station and DRFN technique is applied in case of failure occur in the route obtained by ABC technique.

The remainder of the paper is organized as follows: Section II presents the related work. Section III presents the proposed algorithm and section IV describes the experimental results. Finally, section V concludes the paper.

2. RELATED WORK
In [21] this paper proposed a fault tolerant routing which involves fault recovery process with fault detection scheme, referred to as energy efficient fault tolerant multipath routing scheme for wireless sensor network (FTMRS). In FTMRS technique every sensor node transmits its data to a base station through shortest path. The performance analysis of FTMRS shows better results compared to other popular fault tolerant techniques in wireless sensor networks. In [23] this paper, proposed a novel fault-tolerant distributed multiclass classification fusion approach using error correcting codes (DCFCC) that provides excellent fault-tolerance capability in WSN. This new approach not only provides an improved fault-tolerance capability but also reduces computation time and memory requirements at the fusion center. In [24] this paper, we address the issues of maintaining sensing coverage and connectivity by keeping a minimum number of sensor nodes in the active mode in wireless sensor networks. Based on the optimality conditions, we then devise a decentralized density control algorithm, OGDC (Optimal Geographical Density Control), for density control in large scale sensor networks. [9] proposed a Detection and Replacement of a Failing Node approach for the connectivity maintenance by carrying out a replacement chain according to a distributed algorithm. The main goal of this method is to restore the connectivity of network by using the sensors mobility taking into account the energy constraint. Result shows that the presented method consumes less energy, and improves the percentage of reduction in field coverage as compared to other approaches. [4] proposed a Cluster based Wireless sensor...
network routings using Artificial bee colony algorithm. Result shows that complexity analysis of presented strategy outperforms over direct transmission and LEACH algorithm. [11] presented ABC with real coded crossover operator applied to minimize the length of the tour and find the optimal path. Hence ABC algorithm is used to find shortest path in travelling salesman problem. The experimental result shows that proposed algorithm provides better accuracy and efficiency than the Spanning tree covering algorithm. [20] deals with reducing the make span of the job scheduling task to the minimum by employing Artificial Bee Colony algorithm. In contrast to GA (genetic algorithm), ABC algorithm produced better results. [22] proposed an enhanced DRFN technique by enhancing its failover scheme. The failover scheme will be enhanced using Artificial Bee Colony (ABC) based optimization. It will reduce the overall energy consumption further, and also reduce the number of displacements occur in order to replace the failed node. A novel coverage conscious connectivity restoration (C3R) algorithm is presented in [1]. C3R involves one or multiple neighbors of the failed node to recover from the failure. Each neighbor of the failed node temporarily moves in order to substitute later. Each neighbor involved in the procedure of recovery moved from its original position towards the failed node position in order to perform function of failed node. Energy-centric optimized recovery algorithm (ECR) is also introduced for energy efficiency.

3. PROPOSED ALGORITHM

This section includes the steps of the proposed technique. It presents the methodology of presented algorithm with its steps. In proposed algorithm, firstly sensor nodes are deployed in a square area randomly in Wireless Sensor Networks. In second step, Artificial Bee Colony technique is applied in order to find best or shortest path between sender node and base station. ABC algorithm involve various phases; initialization phase, employed bee phase, onlooker bee phase and scout bee phase. After this step, DRFN technique is applied in case of occurrence of failure of sensor node in the path discovered by Artificial Bee Colony technique. In fourth step of proposed algorithm after failure is detected and removed, rerouting technique is applied to obtain alternative route using Artificial Bee Colony technique. In last step, all the required parameters are evaluated which involve: number of displacements and displacement overhead. The main phases of ABC algorithm are as follows:

i. Initialization: All routes are initialized in the range \( [l_j, u_j] \) by Eq. (1)

\[
x_{ij} = l_j + rand(0,1)(u_j - l_j)
\]

Where \( l_j \) and \( u_j \) is lower and upper bound of route \( x_{ij} \) and \( rand(0,1) \) is a random number between 0 and 1.

ii. Employed bees Phase : Each employed bee is associated with the route and determine new path in its neighborhood by Eq. (2)

\[
n_{ij} = x_{ij} + \phi_{ij}(x_{ij} - x_kj)
\]

Where \( j \) is a randomly chosen parameter and \( k \) is a randomly chosen solution different from \( i \) and \( \phi_{ij} \) is random number within \([-1,1]\).

iii. Onlooker bees phase : Onlooker bees are probabilistically moved to the routes based on the following Eq. (3)

\[
prob_i = \frac{fitness_i}{\sum_{j=1}^{s_n} fitness_j}
\]

Where \( prob_i \) refers to probability of the \( x_i \) route to be selected, \( s_n \) is the number of routes and \( fitness_i \) is the fitness value of the route \( x_i \).

iv. Scout bee phase: Randomly initialize path by a scout bee using Eq. (1)
4. EXPERIMENTAL RESULTS
Simulation in MATLAB is done to determine the performance of ABC-DRFN algorithm. In this simulation, a set of mobile sensor nodes are placed randomly in a 100×100 m² area along x-axis and y-axis to form Wireless Sensor Network.

In this, proposed algorithm performance is compared with existing DRFN algorithm after evaluation of parameters that includes: number of displacements and displacement overheads.

i. Number of displacements: Comparison of displacement number between ABC-DRFN and DRFN is shown in Table 1. From graph shown in Figure 3, it is clear that number of displacements in ABC-DRFN is less than number of displacements in DRFN where x-axis represents number of rounds and y-axis represents number of displacements.

<table>
<thead>
<tr>
<th>Rounds</th>
<th>DRFN</th>
<th>ABC-DRFN</th>
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<tbody>
<tr>
<td>15</td>
<td>3.0000</td>
<td>2.4000</td>
</tr>
<tr>
<td>25</td>
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<td>3.6400</td>
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<tr>
<td>35</td>
<td>6.3429</td>
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<tr>
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<td>8.6308</td>
</tr>
<tr>
<td>75</td>
<td>13.000</td>
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<tr>
<td>95</td>
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<td>12.3789</td>
</tr>
</tbody>
</table>

![Flowchart of proposed algorithm](image1.png)

![Self-Organized Data Collecting and Transmitting Phase of DRFN](image2.png)

![Number of displacements in DRFN and ABC-DRFN](image3.png)
ii. Displacement overheads: Comparison of displacement overhead between ABC-DRFN and DRFN is shown in Table 2. From graph shown in Figure 4, it is clear that displacement overhead occur in ABC-DRFN is less than overheads occur in DRFN where x-axis represents number of rounds and y-axis represents displacements overheads.

Table 2 Comparison of displacement overheads in DRFN and ABC-DRFN.

<table>
<thead>
<tr>
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<th>ABC-DRFN</th>
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<tr>
<td>95</td>
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<td>0.2396</td>
</tr>
</tbody>
</table>

Fig. 4 Displacement overheads in DRFN and ABC-DRFN.

5. CONCLUSION

Sensor nodes in Wireless Sensor Networks may fail due to limitation of energy or less power supply and harsh environment in which it is deployed. In this paper we proposed an improved DRFN technique by improving its failover mechanism. The failure handling mechanism would be improved by using Artificial Bee Colony (ABC) based optimization technique. The presented technique has decreased the occurrence of displacements and also reduces displacement overheads. Result of simulation shows that the proposed technique performs better than existing technique.

6. REFERENCES


