Abstract

In this paper, the solution of the matrix Riccati differential equation (MRDE) for nonlinear singular system is obtained using neural networks. The goal is to provide optimal control with reduced calculus effort by comparing the solutions of the MRDE obtained from well known traditional Runge Kutta (RK) method and nontraditional neural network method. Accuracy of the neural solution to the problem is qualitatively better. The advantage of the proposed approach is that, once the network is trained, it allows instantaneous evaluation of solution at any desired number of points spending negligible computing time and memory. The computation time of the proposed method is shorter than the traditional RK method. An illustrative numerical example is presented for the proposed method.

Reference


[24] K. S. Narendra and F. L. Lewis, Special issue on neural network feedback control,
Solution of matrix Riccati differential equation for nonlinear singular system using neural networks

Automatica, 37 (2001), 1147-1148.


Index Terms

Computer Science

Singular Systems

Key words

Matrix Riccati differential equation

Nonlinear

Optimal control
Solution of matrix Riccati differential equation for nonlinear singular system using neural networks

Singular system

Runge Kutta method and Neural networks