

Result Analysis and Comparison of Hybrid Method based on Local Binary Pattern (LBP) and Color Moment (CM) for Efficient Image Retrieval

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ABSTRACT

In this paper LBP and CM methods have been efficiently used for image retrieval for the content based image retrieval (CBIR) system. As LBP method may be sensible to noise in case of comparing neighboring pixels. The drawback of CM is it may be inefficient with too much details image. So it will be better to combine the feature of both method and utilized the property of both the two methods. In this paper LBP and CM are used combined along with the analysis of individual LBP and CM for the comparison. Wang database have been used for the experimentation. All the 10 classes are used for the results comparison. The results suggested that the combined method have the capability over individual methods in efficient image retrieval.

Keywords

CBIR, Content Retrieval, LBP and CM

1. INTRODUCTION

Visual analysis is an emerging trend in research arena. CBIR system is more trending now a days because of the demand of efficient image retrieval system [1]. The demand of efficient image retrieval system is the need of the current edge so that picture information is extracted properly [2-4]. Image information solidifies the noisy pictures and data secluded from pictures through electronic or recreated estimations [5].

CBIR systems are similarly working with the same lay [6]. A section vector is ousted from each photo in the database and the course of action of all highlight vectors is encircled as a database record [7]. At the time, a substitution vector is removed from the solicitation picture other than; it is energized against the section vectors in the record [8-16]. The key differentiation between the specific structures lies in the parts that they empty and in the counts that are utilized to take a gander at highlight vectors [17]. The shading is the most by and large used visual fragments as a piece of picture recuperation in light of the way that they are less requesting to withdraw isolated and surface and shape information. Shading highlight is acceptably ready to establishment multifaceted nature and free of picture size and presentation. Quantifiably, it demonstrates the joint probability of the intensities of the three shading channels [18]. Blends of timetables have been made for measuring strategy equivalence [19]. Most systems rely on upon in the wake of taking a gander at estimations of what are known as second-demand estimations enrolled from sales and set away pictures [20]. These timetables figure measures of picture surface, for instance, the level of refinement, coarseness, directionality and consistency [21]; or periodicity, directionality and intercession [22]. Elective system for surface examination for picture recuperation

merges the utilization of Gabor channels [23] and fractals [24].

2. RELATED WORKS

In 2011, Jain et al. [25] suggested that the CBIR is a widely used procedure which is capable in finding images from huge image databases. With expansive information sets, there is probability of high dimensionality. In 2012, Das et al. [26] implemented a CBIR system which uses different feature of images by applying four methods, two methods were based on the color feature analysis and rest two were based on color and texture feature analysis using wavelet coefficients of an image. In 2007, Jain et al. [27] proposed an algorithm for retrieving images. The algorithm uses the shape information in an image along with its 3D information. The calculation utilizes the shape data as a part of a picture alongside its 3D data. In 2014, Wan et al. [28] suggested that the learning representations and similarity measures are very important for CBIR system. They have suggested that semantic gap issue which can be exists in the low-level image pixels which are only captured by machines and high-level semantic concepts perceived by human. In 2006, Heller et al. [29] presented a Bayesian framework for CBIR which is capable in modeling the distribution of color and texture features within sets of related images. They suggested that for a user specified content question the framework first concentrates an arrangement of images, from a named corpus, relating to that question. In 2012, Chaudhari et al. [30] suggested that the CBIR uses the visual properties of an image such as color, shape, texture, and spatial layout to represent and index the image. In 2015 Dubey et al. [31-34] suggested that data mining and evolutionary algorithms can be useful in improving the classification accuracy. So there used techniques may be helpful in image retrieval and proper classification. In 2007, Liu et al. [3] provided a comprehensive survey of the recent technical achievements in high-level semantic-based image retrieval. In 2015, Alzu'bi et al. [35] suggested that the multimedia contents complexity is increasing dominantly in the current digital world. So this generates the need of highly effective retrieval systems. In 2012, Jain et al. [36] presented an efficient framework with the combination of color, texture and shape information. They have applied the coordination of the above and bunch in view of alike properties. In view of five predominant colors they recover the comparative pictures. In 2013, Bhagat et al. [37] suggested that the execution of an electronic extensible design that is effortlessly indispensable with applications written in various dialects and linkable with various information sources. In [38] author has presented a brief survey on CBIR techniques.

3. METHODS

In this paper LBP and CM methods are applied for the efficient image retrieval technique. It is a part of CBIR system which means content based image retrieval system. In this the data has been searched based on the content. Content indicates the colors, shapes and textures. LBP is used here as it is efficient in thresholding the neighborhood for every pixel. By this classification accuracy can be improved and it can help in feature selection [39]. CM is useful in indexing the images based on the color in image retrieval system as it provides image retrieval based on color index. For result validation Wang database have been used [40] [41]. It is a collection of 1000 database.

LBP

In this method of image retrieval first the color images are converted to gray scale. As it works only on gray scale images. As we have already discussed that it is efficient in neighborhood pixel selection and thresholding. Then LBP values for the corresponding pixels are calculated. Then corresponding pixel location is updated in the data matrix or used as the LBP mask vector. The neighboring pixel values are then compared with the central pixel value to calculate the pixel LBP value. It can be calculated for all the pixels. This can be done by traversing in the same order of clock or anti-clock wise position with the same position. So the comparison is depends on the pixels. It is started from the initial pixel. These values are between 0 to 255. The main benefit of using LBP is translation invariant property.

The whole image is considered for the process. LBP method is capable enough to extract the local information. It helps in extracting local features of an object. The main concept behind using the LBP technique is to calculate the local structure of an image by comparing the pixels with the neighborhood.

$$LBP(X_c, Y_c) = \sum_{n=0}^{n-1} 2^n Q(I_n - I_c)$$

Where X_c and Y_c denotes the central pixel. Q can be understood as follows:

$$Q(X) = \begin{cases} 1 & \text{if } x \geq 0 \\ 0 & \text{else} \end{cases}$$

I_n denote the neighbor pixel intensity. I_c denotes the central pixel intensity.

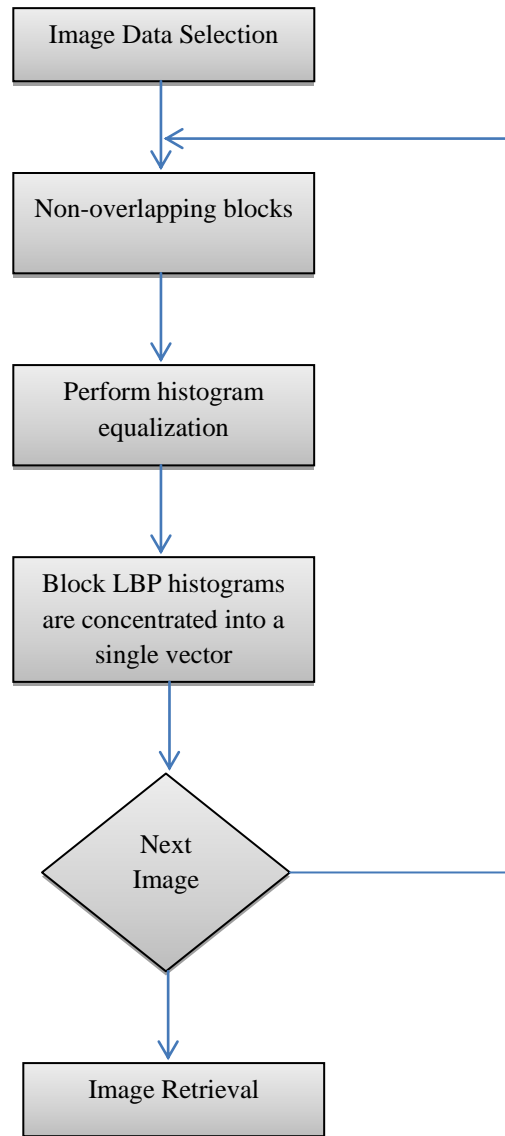


Figure 1: Process flowchart of LBP

For the calculated center vector X_c and Y_c the position of the neighbor in the LBP can be calculated as follows:

$$X_n = X_c + R \cos \frac{2\pi n}{S}$$

$$Y_n = Y_c - R \sin \frac{2\pi n}{S}$$

Where R denotes radius and S is the sample point.

CM

It is a supportive measurement which can be used to differentiate images based on the color feature. It is calculated based on the similarity of images. This can be basically determined by the normal distribution or by calculating their mean and variance. It shows a pattern of moment which can help in identifying the image based on color. Three moments are used mainly mean, standard deviation and skewness. The color can be defined as the Hue, Saturation and brightness. Then the moments are calculated for the separate channel in the picture. Color moment can be formulated as follows:

Suppose there are n observations like X_1, X_2, \dots, X_n belong

to X variable. The average of X_1, X_2, \dots, X_n can be represented as is the mean, μ_X , denoted as follows:

$$\mu_X = \bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

Then the standard deviation can be calculated as follows:

$$\sigma_X = \sqrt{\sigma_X^2}. \text{ We have}$$

$$\sigma_X = \sqrt{\frac{1}{n} \left\{ \sum_{i=1}^n X_i^2 - \frac{1}{n} \left(\sum_{i=1}^n X_i \right)^2 \right\}}$$

According to the Karl skewness can be defined as follows:

$$sk = \frac{\mu - \text{mode}}{\sigma}$$

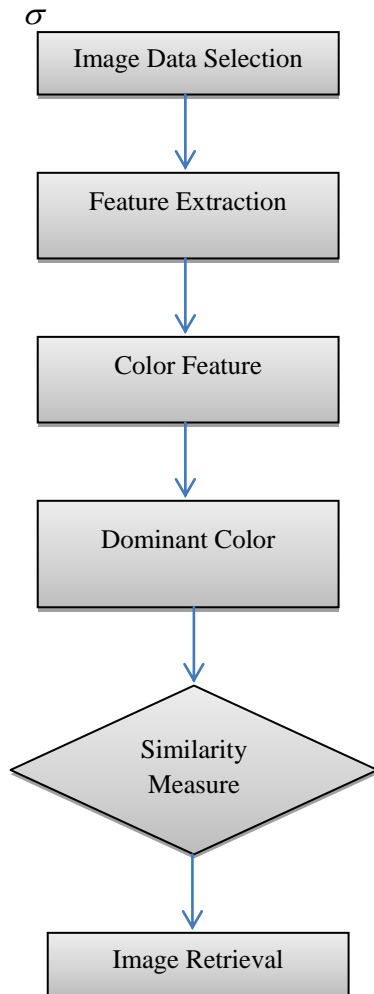


Figure 2: Process flowchart of CM

The group of color extracted based on the dominant color which is the combination of color fetched. Before separating the color attributes of a picture, all pixels on database pictures are arranged into comparable sorts of gatherings as per the similarity of their hues. A color will be chosen from predefined hues which are exceptionally close to picture pixel color and it is stored as a new pixel. Color distance C_D can be measured by adopting Euclidean distance equation as specified below:

$$C_D = \min (\sqrt{(R_p - R_{iT})^2 + (G_p - G_{iT})^2 + (B_p - B_{iT})^2})$$

R_p, G_p and B_p are the color intensity values of red, green, and blue colors respectively. R_{iT}, G_{iT} and B_{iT} are the color table index. The maximum percentage color component is selected as the dominant color and stored.

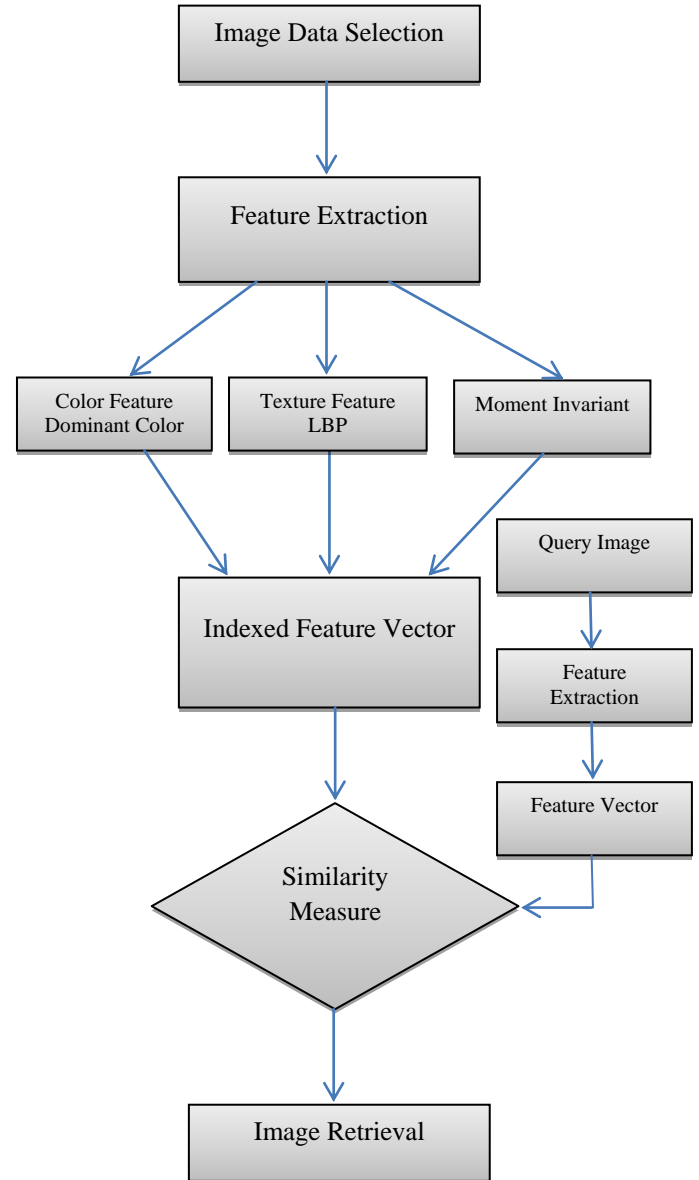


Figure 3: Combined flowchart for LBP and CM

For similarity measurement from the experimental images can be calculated as follows by the Euclidean distance, d using equation below:

$$d = \sqrt{(F_Q[i] - F_{DB}[i])^2}$$

$F_Q[i]$ denotes i^{th} feature of the query image and the $F_{DB}[i]$ indicates the related feature in the feature vector.

So it can be said that in color moment the images are first selected and moment for the query images are calculated then dominant color is used for the color feature extraction then similarity is calculated based on the rank.

In this paper we have combined these two methodologies for achieving the better results.

4. RESULTS AND DISCUSSION

The results are compared based on the Wang database. All the ten classes are considered for experimentation. Figure 4 and figure 5 shows the process of LBP and CM. Different variations have been found in the results. It can suggest that the results are varying based on the properties of the images. Figure 6 shows the results based on the hybrid method and provide better results than individually applying LBP and CM. Table 1 and figure 7 shows the overall comparison based on the LBP, CM and LBP + CM. It shows that the results outperforms in case of hybridization.

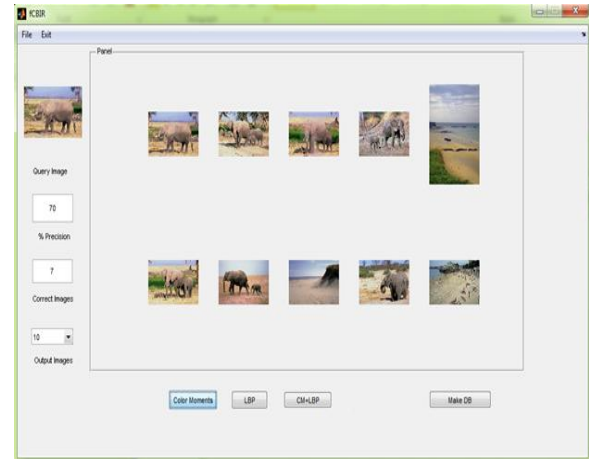


Figure 5: CM for image database

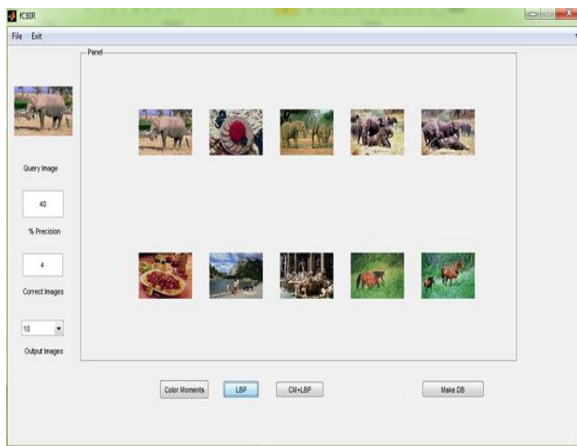


Figure 4: LBP for image database

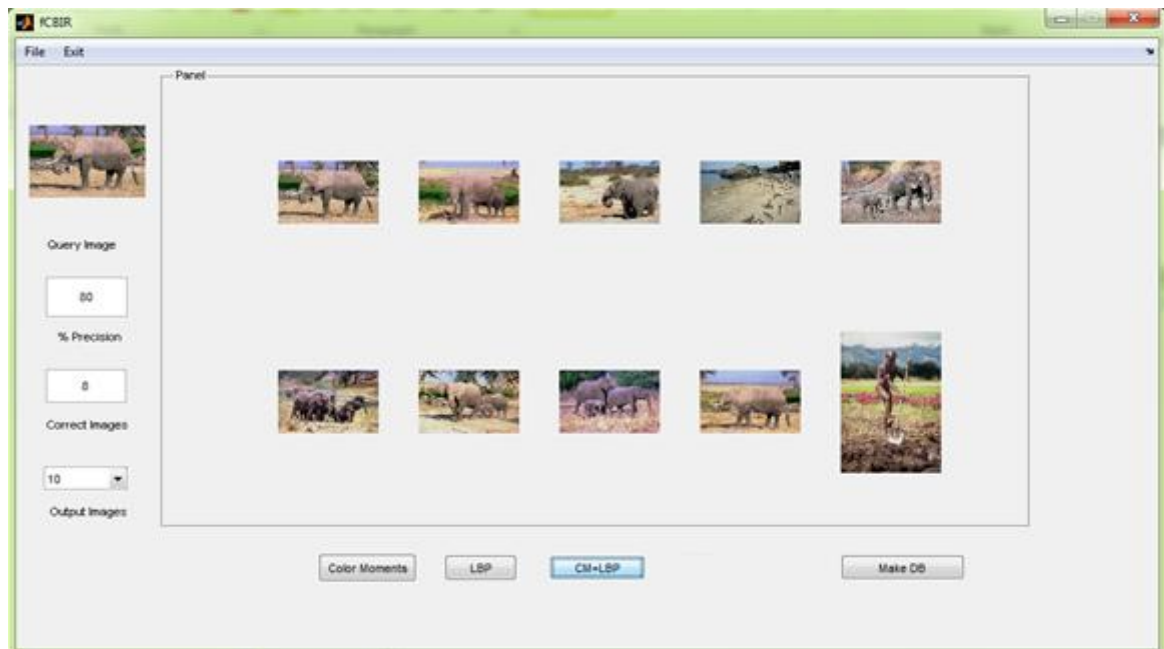


Figure 6: LBP + CM for image database

Table 1: Previous work comparisons

S.no	Database Image	Precision Method1-LBP (%)	Precision Method2-CM (%)	Precision Method3-CM +LBP (%)
1	1	80	80	80
2	157	60	80	80
3	219	10	30	30

4	314	90	90	90
5	400	100	100	100
6	510	40	70	80
7	640	90	70	70
8	716	80	40	40
9	814	30	80	60
10	906	70	100	100

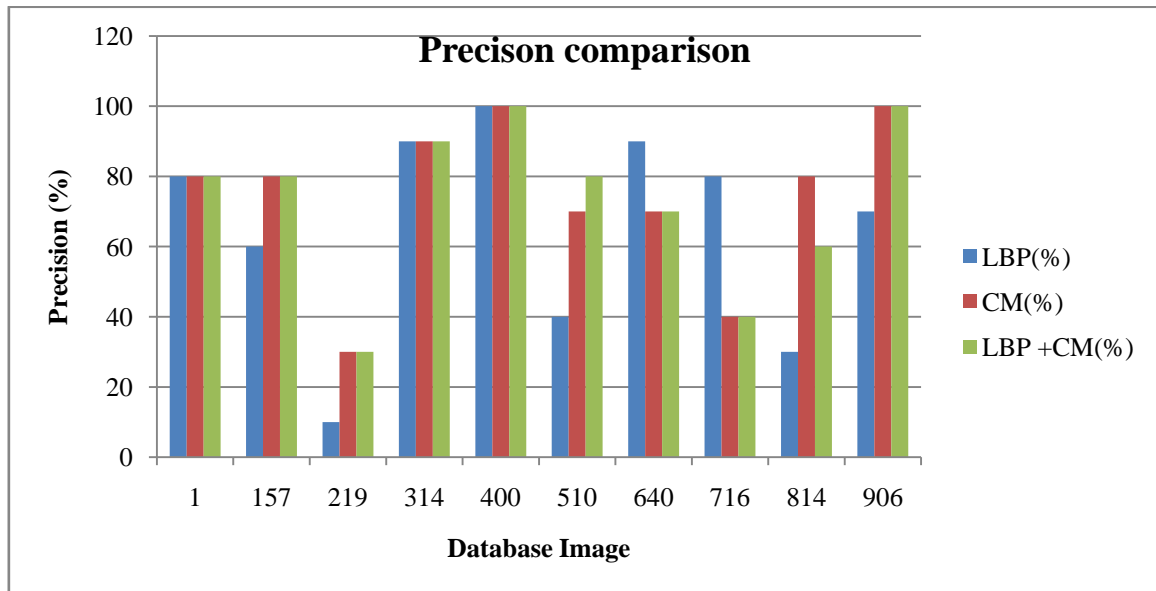


Figure 7: Comparative Table

5. CONCLUSIONS

In this paper LBP, CM and LBP + CM for the image retrieval based on CBIR system have been analyzed and discussed. The results have been discussed based on the LBP and CM. But the results obtained are variant and supports different combinations. But in the case of hybridization of LBP + CM better results have been obtained in comparison to using it individually.

6. REFERENCES

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