Abstract

Stepper motors have already shown their advantages of use in applications where precision movements and accurate control are required. One of the most commonly used type of controller that was used to control stepper motors is the classical PID controller because of its easily programming characteristics. In this paper such a conjunction is going to be presented and as well as all the results of a given example of application.

References

3. P. S. Huang, C. S. Chiang, C. P. Chang, and T. M. Tu, "Robust spatial watermarking


Index Terms

Computer Science

Control Systems

Keywords
Stepper motor, classical controllers, PID method, three terms tuning