The Evaluation of Software Solutions for Reliability using Modified Musa's Basic Execution Time Model

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ABSTRACT

Software systems have gained great significance for most organizations on an operational as well as a strategic level. Failures before delivery or more often changes in existing software systems are stochastic processes and it is important for programmers (or users) to predict reliability of software product they are developing (or using) in order to accept that as business risk. In this paper we have used the Modified Musa Basic Execution Time Model to show how to evaluate a solution called electronic Nursing healthcare Care Management System (eNCMS). We used black box testing to ascertain that the software achieved it basic functions. Five (5) patient records collected from Obafemi Awolowo University Teaching Hospital Complex (OAUTHC) were used during this evaluation and the outcome shows that the system achieved 75% reliability.

Keywords

Black box, reliability, healthcare, software reliability testing, testing.

1. INTRODUCTION

Software evaluation is the process of executing a program or system with the intent of finding errors. Or, it involves any activity aimed at evaluating an attribute or capability of a program or system and determining that it meets its required results. Software is not unlike other physical processes where inputs are received and outputs are produced. Where software differs is in the manner in which it fails. Most physical systems fail in a fixed (and reasonably small) set of ways. By contrast, software can fail in many bizarre ways [1].

Software reliability refers to the probability of failure-free operation of a system. It is related to many aspects of software, including the testing process [2]. Directly estimating software reliability by quantifying its related factors can be difficult. Testing is an effective sampling method to measure software reliability. Guided by the operational profile, software testing can be used to obtain failure data, and an estimation model can be further used to analyse the data to estimate the present reliability and predict future reliability [3]. Therefore, based on the estimation, the developers can decide whether to release the software, and the users can decide whether to adopt and use the software. Risk of using software can also be assessed based on reliability information.

Reliability Testing is very important, as it discover all the failures of a system and removes them before the system is deployed. This also determines the failure rate or failure intensity of a system. Software reliability is the measured in terms of failure intensity which is the number of failures per unit time. Reliability testing is related to many aspects of software in which testing process is included; this testing process is an effective sampling method to measure software Onyekware U. Oluoha Department of Computer Science University of Nigeria, Nsukka

reliability. Robustness testing and stress testing are the variances of reliability testing. Robustness refers to how software component works under stressful environmental conditions. Robustness testing only watches the robustness problem such as machine crashes, abnormal terminations etc. [3].

Software reliability is one of the main factors to measure the quality of software. Since software errors cause spectacular failures in some cases, we need to measure the reliability factor to determine the quality of software product, predict reliability in the future, and use it for planning resources needed to fix failures. Software reliability models are applicable tools to analyze software in order to evaluate the reliability of software [1]. During the past twenty-five years, more than fifty different models have been proposed for estimating software reliability but many of software practitioners do not know how to utilize these models to evaluate their products. In this paper we will present a survey on different models of software reliability and their characteristics. We will propose taxonomy of different models and try to aid the comprehension of these models for practitioners, developers, and users. In the last section we apply some of these models on two different open source projects and compare the results.

2. BLACKBOX TESTING

This testing methodology looks at the available inputs for an application and what the expected outputs should result from each input. It is not concerned with the inner workings of the application, the process that the application undertakes to achieve a particular output or any other internal aspect of the application that may be involved in the transformation of an input into an output [4]. Most black-box testing tools employ either coordinate based interaction with the applications graphical user interface or image recognition. An example of a black box system would be a search engine. You enter text that you want to search for in the search bar, press "Search" and results are returned to you. In such a case, you do not know or see the specific process that is being employed to obtain your search results, you simply see that you provide an input-a search term-and you receive an output-your search results.

Black box testing, also called functional testing and behavioural testing, focuses on determining whether or not a program does what it is supposed to do based on its functional requirements [2]. Black box testing attempts to find errors in the external behaviour of the code in the following categories: (1) incorrect or missing functionality; (2) interface errors; (3) errors in data structures used by interfaces; (4) behaviours or performance errors; and (5) initialization and termination errors. Through this testing, we can determine if the functions appear to work according to specifications. However, it is important to note that no amount of testing can unequivocally demonstrate the absence of errors and defects in a program. The beauty of black box testing is seen when the tester is not the programmer of the code and knows nothing about the structure of the code [5].

3. MUSA'S BASIC EXECUTION TIME MODEL

The Musa's Basic Execution Time Model is an example of a prediction model [3]. Prediction models are used to make software reliability predictions early in the development phase that help make software engineering decisions in the design stage. Musa's Basic Execution Time Model is important to the field of software reliability because it was created by John Musa of AT&T Bell Laboratories who is often credited as the pioneer of software reliability[2]. Musa's Basic Execution Time Model was one of the first software reliability models used to model reliability based on the execution time of software components instead of the calendar time components are in use. Since the time between failures can be expressed in terms of CPU (central processing unit) time, Musa's Basic Execution Time Model can accurately indicate the actual stress on the software system. Musa's Basic Execution Time Model calculates the reliability of a software system using the Poisson distribution. The model assumes the execution time between failures has piecewise exponential distribution, the hazard rate of a single fault is constant, faults are removed with certainty and reoccurring failures caused by a single fault are not counted [5]. The data required to implement Musa's Basic Execution Time Model include the time elapsed between software failure and the actual calendar time the software was in use. Musa's Basic Execution Time Model is useful when predicting why a software system might fail when deployed. Musa's Basic Execution Time Model has been used to calculate the reliability of land line telephone software. Musa's Basic Execution Time Model is a good reliability model to use when the model is based on sound assumptions and a simple model is both desired and achievable. Because of the above-mentioned reasons, the simplicity and ease of use, this model is employed in this research to evaluate the system.

Since in this case, the focus is on reliability testing, both white box and black box testing techniques were employed, the white box testing was done by the developer and the result was evaluated using the extended or modified Musa's software reliability model which is discussed in this section. The black box testing was done by some registered nurses and the result was also evaluated using extended Musa's model. In both cases of the testing, the extent to which the system could go without failure was determined.

Since the system is made up of different modules or functional components, testing these different components gives the most accurate result for the reliability of the system since the testing leads to the dynamic verification of the behaviour of each module on a finite set of the test cases which are suitably selected from the usually infinite executions domain, against the specified expected behaviour. The testing effort is divided into test case generation, test execution, test evaluation. To reduce the cost of testing process, efficient test case generation technique is required. The reliability of the functional components of the system was then computed using the modified Musa's Basic Execution Time Model [1]. This model was chosen because it is very simple to use and can determine the maximum errors in the system without taking much time.

With this model, it is possible to predict the final number of failures (usually denoted by v_0) that will be detected in the future, after the system delivery. This software reliability growth models assume that software failures occur as a random non-homogeneous Poisson process (NHPP) and it is possible to evaluate Markov models from NHPP models and predict system's reliability by solving state equations with numerical integration [1]. The model used in this section called modified Musa Basic execution time is based on the following basic assumptions where the cumulative number of failures experienced at time *t* is N(t) [1]:

- i. There are no failures to begin with (for t=0,N(t)=N(0)=0)
- ii. The failures are independent, the number of failures experienced during the interval (t, t+h) is independent of the past history, N(t)
- iii. The probability that a failure will occur during (t, t+h) is:

$$P(N(t+h) - N(t) = 1) = \lambda(t)h + o(h) \quad (0.1)$$

Where o(h) is negligible when *h* is small. There are no simultaneous failures.

iv. The probability that more than one failure will occur during (t, t+h) is o(h)

$$P(N(t+h) - N(t) > 1) = o(h) (0.2)$$

Failure rate is time dependent. This describes a Non-Homogeneous Poisson Process where λ is a failure rate and varies with time. There are different NHPP models connected with the representation of $\lambda(t)$ function. The mean value of failure distribution is:

$$E[N(t)] = \mu(t) = \int_0^t \lambda(\tau) d\tau \qquad (0.3)$$

Where $\mu(t)$ is the expected number of cumulative failures at time t. In order to derive this model, it is assumed that we can estimate the expected number of total failures ν_0 can be determined. It can be assumed that the initial failure rate λ_0 can be predicted if *n* is the mean cumulative number of failures experienced at some point in the testing process, then the basic failure rate is expressed as:

$$\lambda(n) = \lambda_0 (1 - \frac{\nu}{\nu_0}) \tag{0.4}$$

Where: λ_0 = initial failure rate, ν = average number of failures experienced at a given point in time ν_0 = total number of failures in the program, detected if given infinite time. In this model, the failure rate $\lambda(n)$ is a linear function of the experienced software failure. The rate of change of $\lambda(\nu)$ can be determined by taking the derivative:

$$\frac{d}{d\nu}\lambda(n) = -\frac{\lambda_0}{\nu_0} \tag{0.5}$$

If the decrement of the software failure rate per failure is denoted as:

$$\beta = \frac{\lambda_0}{\nu_0} \,. \tag{0.6}$$

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Then the failure rate is expressed as:

$$\lambda(n) = \beta(\nu_0 - \nu) \tag{0.7}$$

Since the mean number of software failures is experienced as a function of the execution time *t*, it is:

$$\lambda(t) = \beta \left[(\nu_0 - \mu(t)) \right] \tag{0.8}$$

Since $\mu(t)$ is the time integral of $\lambda(t)$ it follows that $\lambda(t)$ is the derivate of $\mu(t)$. Then the equation can be rewritten as:

$$\frac{d}{dt}\mu(t) + \beta\mu(t) = \beta\nu_0 \tag{0.9}$$

With solving of the above differential equation for $\mu(t)$ it is obtained:

$$\mu(t) = \nu_0 (1 - \exp[-\beta t])$$
(0.10)

The failure rate can be obtained by:

$$\frac{d}{dt}\mu(t) = \lambda(t) = \beta \nu_0 \exp\left[-\beta t\right] \qquad (0.11)$$

In either case, failure rate function decreases exponentially to 0 and the initial failure rate is evaluated (at t=0) as:

$$\lambda_0 = \nu_0 \beta \tag{0.12}$$

In addition to the basic execution time model described in this section, many others have been proposed in the past. One with the widest distribution among the software reliability models was deployed by John Musa during his work at AT&T Bell Laboratories (*Musa, 1993*). Including the standard assumptions above, the basic assumptions for Musa's basic execution time model are:

- i. The cumulative number of failures by time *t*, follows a Poisson process with mean value function $\mu(t) = \mathcal{V}_0(1 \exp[-\beta t])$, where \mathcal{V}_0 , $\beta > 0$. The mean value function is such that the expected number of failure occurrences for anytime period is proportional to the expected number of undetected faults at that time.
- ii. Used model is a finite failure model.

Suppose n observed failures of the software system at times t_1 , t_2 ,..., t_n and from the last failure time t_n an additional time of x (x>=0) elapsed without failure ($(t_n + x)$) is therefore the total time the software component has been observed since the start). Using the model assumptions, the likelihood function (Musa, 1993) is obtained as:

$$L(\nu_{0},\beta) = \nu_{0}^{n}\beta^{n}[\Pi_{i=1}^{n}\exp(-\beta t_{i})]\exp(-\nu_{0}[1 - \exp((t_{n} + x))])] (0.13)$$

The maximum likelihood estimates (MLEs) [1] of ν_0 and β are obtained as the solutions to the following pair of equations:

$$\nu_0 = \frac{n}{1 - \exp(-\beta(t_n + x))}$$
(0.14)

$$\frac{n}{\beta} - \frac{n(t_n + x)}{\exp(\beta(t_n + x)) - 1} - \sum_{i=0}^n t_i = 0$$
(0.15)

Once the estimates of ν_0 and β are obtained, it is possible to use the invariance property of the MLEs to estimate other reliability measures like reliability function, hazard rate, failure intensity function etc.. This approach is then use to evaluate our system.

4. CASE STUDY: THE ELECTRONIC NURSING CARE MANAGEMENT SYSTEM

This application is a comprehensive, integrated information system designed to manage the patient care, administrative, financial and legal aspects of nursing. The solution can also be used to monitor staffing levels and achieve more costeffective staffing. Nurses could also use it for admission information, care plan and all relevant nursing notes. All important data is securely stored and can be retrieved when required. All these features in this system ultimately lead to a reduction in planning time and better assessments and evaluations.

The essence of this section is to evaluate the errors identified while testing this system. The system has achieved its main objective; hence evaluation of errors should not be taken as failure of the system to achieve its objective but a way to ascertain how reliable the system is. The components of this system all interact together to produce the care plan. This system is made up of five (5) components: user management, NNN linkage [6], patient registration, the nursing process and nursing history. The User Management Module: Users are entities that can be authenticated. Each user is assigned a unique identity within the realm. To make it easier to administer a large number of users, users can be organized into named groups. This system uses single-sign-on which implies that all users must login through a single interface and are authenticated before authorizing them to access the system resources. Authorization involves granting an entity permissions and rights to perform certain actions on a resource. In role-based authorization, security policies define the roles that are authorized to access the resource. This module is responsible for adding new staff and assigning login credentials (username and password) to them. It also reminds the staff when they are supposed to implement a care for a particular patient; and add information relating to the health facility setting (wards, rooms, etc.). The NNN Linkage Module: This module handles the adding of NANDA-I diagnoses [7][8], NOC outcomes [9] and NIC interventions [10]; and also establish the linkage among these three (3) languages. This link the NANDA-I diagnoses to NOC outcomes; these are the linked to the NIC interventions. This follow the sequence described in [6] in linking NANDA-I, NOC and NIC. The NANDA-I diagnoses are identified. The Patient Registration Module: This module is responsible for adding or updating patients' information. These include personal information, next of kin information, educational information, employment information, etc. It also handles the admission of patient into the system. During the admission process, a visit number is generated for the patient which is used to track everything about the patient for a particular visit. This visit number increases by one for every visit. The Nursing Process Module: The nursing process module is responsible for the implementation of the five (5) phases [11] of the nursing process-assessment, nursing diagnosing, planning, implementation and evaluation. Nursing care plan

being the blueprint of this process is generated as well. The assessment phase in this system is based on the Gordon's functional health patterns [11]. **The Nursing History Module:** This keeps the archive of all the activities that are carried out on the system.

The NNN Linkage module creates the library for nursing diagnoses, outcomes and interventions. During the development of the care plan, reference is made to this module to get the diagnoses, outcomes and interventions. The nursing process module enables the nurse to create the nursing care plan. This module is central to all the other modules. The history module is the module that keeps track of all the activities of the nurses during the implementation of the nursing process. The reliability of these components implies the reliability of the whole system.

The evaluation of this system was carried out in two phases. First, the functional components of the system were tested with some existing care plans to see if the output tallies with those care plans; any deviation from that result into a failure. Therefore, failure here is not system failure or error but deviation from the expected output. The functional components and their respective functions are shown in table 1. In the second phase, the failure log resulting from the testing is evaluated using the reliability model described above and the result is represented on graphs.

Software reliability is therefore centred around software faults, their effect on the system and the remaining number of faults, system failures, the way of detecting failures, time between failures and failure rates (or failure intensities), as well as the confidence in the performed estimates. Identifying faults and removing them leads to the decrease of the system failure rate and the increase of the system reliability with time. The cumulative number of errors detected and corrected increases with the passage of time. This makes the software reliability curve to look like a demand curve. In order to evaluate this system, the model described in section 3 will be used. The standard assumptions for this model are:

- i. The rate of fault detection is proportional to the current fault content of software.
- ii. The fault detection rate remains constant over the intervals between fault occurrences
- iii. A fault is corrected instantaneously without introducing new faults into the software
- iv. The software is operated in a similar manner as that in which reliability predictions are to be made
- v. Every fault has the same chance of being encountered within a severity class as any other fault in that class
- vi. The failures, when the faults are detected, are independent

The system was tested using five (5) patient data collected from Obafemi Awolowo University Teaching Hospital Complex (OAUTHC), Ile-Ife, Nigeria.

Table 1. Test Cases for Black box Testing

Module	Function	Result	No of Runs
User Management	Create Users	Ok	5
	Login	Ok	5

	-		-
	Logout	Ok	5
	Check Profile	Ok	5
	Change password		5
NNN Create NANDA-I Linkage		Ok	5
	Create NOC	Ok	5
	Create NIC	Ok	5
	Link NANDA-I to NOC to NIC	Ok	5
Patient Registration	Register patient	Ok	5
	Admit patient	Ok	5
Nursing Process	Create assessment using Gordon's health patterns	Ok	5
	Upload and cluster cues	Ok	5
	Identify diagnoses and expected outcomes	Ok	5
	Upload planned interventions and view the care plan	Ok	5
	Implement the care plan	Ok	5
	Evaluate the care plan and view the evaluated care plan	Ok	5
Nursing History	View History of all the Activities carried out	Ok	5

 Table 2. Failure Log for black box Testing (0.5 hour) for

 User Management Module

No of Time	New Failure Detected
1	3
2	0
3	1
4	1
5	1

 Table 3. Failure Log for black box Testing (0.5 hour) for

 Patient Registration Module

No of Time	New Failure Detected
1	2
2	1
3	0
4	1
5	1

No of Time	New Failure Detected
1	10
2	3
3	3
4	1
5	1

Table 4. Failure Log for black box Testing (3 hours) for Nursing Process Module

Table 5. Failure Log for black box Testing (0.5 hours) for NNN Linkage Module

No of Time	New Failure Detected
1	4
2	0
3	1
4	1
5	1

 Table 6. Failure Log for black box Testing (0.5 hours) for

 Nursing History Module

No of Time	New Failure Detected
1	3
2	1
3	2
4	0
5	0

The Fig. 1, Fig. 2, Fig. 3, Fig. 4 and Fig. 5; derived their values from Table 2, Table 3, Table 4, Table 5 and Table 6 respectively. Looking at the graphs for the black box testing of the modules, they all slope downward from left to right just like a demand curve. This is because as the software is tested, faults are identified and corrected which reduces the number of faults present in the system thereby making the curve to start from a higher frequency and slope down to a lower one. On the other hand, as these faults are identified and corrected, new faults are introduced which make curve to move up and down which makes the curves not to be smooth.

The cumulative number of errors is a function that increases with time and asymptotically approaches the total number of errors V_0 . By systematically detecting failures and removing faults, it is possible to achieve the required system mean time to failure (MTTF). The curve for the cumulative failure rate for the black box testing of the five functional modules of the system is shown in fig. 6. Here, we arrived at V_0 after testing all the modules several times and its value is 8. This is because no new failure was detected after this was achieved. This shows that the software is very reliable.







Fig. 2: Graph for the black box testing of the Patient Registration Module



Fig. 3: Graph for the black box testing of the Nursing Process Module



Fig. 4: Graph for the black box testing of the NNN Linkage Module



Fig. 5: Graph for the black box testing of the Nursing History Module

Table 7. Failure Log for Black box testing for 5hrs

Time (hrs)	No. of Times	Failure	Cumulative Failure	Module
0.5	5	1	1	User Management
3.5	5	1	2	Nursing Process
4.0	5	1	3	Patient Registration
4.5	5	1	4	NNN Linkage
5.0	5	0	4	Nursing History

According to Table 7 and equations (0.14) and (0.15), the maximum likelihood estimates of \mathcal{V}_0 and β are the solution of the following equations:

$$\nu_0 = \frac{n}{1 - \exp\left(-\beta(t_n + x)\right)} \frac{n}{\beta} - \frac{n(t_n + x)}{\exp\left(\beta(t_n + x)\right) - 1} - \sum_{i=0}^n t_i = 0$$

If n=4,
$$(t_n + x) = 5$$
, $\sum_{i=0}^{n} t_i = 12.5$

Substituting the values

$$\nu_0 = \frac{4}{1 - \exp(-5\beta)} \tag{0.16}$$

$$\frac{4}{\beta} - \frac{20}{\exp(5\beta) - 1} - 12.5 = 0 \tag{0.17}$$

Using power series to expand $\exp(5\beta)$

$$\exp(5\beta) = \sum_{i=0}^{n} \frac{(5\beta)^n}{n!}$$

If n=4

$$\exp(10\beta) = \frac{(5\beta)^0}{0!} + \frac{(5\beta)^1}{1!} + \frac{(5\beta)^2}{2!} + \frac{(5\beta)^3}{3!}$$
$$\exp(5\beta) = 1 + 5\beta + \frac{(5\beta)^2}{2} + \frac{(5\beta)^3}{6} \qquad (0.18)$$

Substituting (4.6) into (4.5), we have

$$\frac{4}{\beta} - \frac{20}{1 + 5\beta + \frac{(5\beta)^2}{2} + \frac{(5\beta)^3}{6} - 1} - 12.5 = 0$$

Expanding the equation above leads to a quadratic equation as given below

$$1562.5\beta^2 + 437.5\beta + 75 = 0$$

a=1562.5, b=437.5 and c=75

Using quadratic formula, we have

$$\beta = -0.14$$
 twice

But β cannot be negative, therefore, $\beta = 0.14$, substituting the value of β in (0.16), we have

$$\nu_0 = \frac{4}{1 - \exp(-5\beta)}$$
$$\nu_0 = \frac{4}{1 - \exp(-0.7)}$$
$$\nu_0 = 7.9457$$

But the total number of failures cannot be a fraction, therefore, the value of our ν_0 will be 8 instead of 7.9457.

With these results we can expect final number of the failures that are caused by errors in software design.

If the values of β and ν_0 are known then is possible to draw model graph of cumulative failures with using of equation (0.10).

$$\mu(t) = \nu_0 (1 - \exp\left[-\beta t\right])$$

Comparison of cumulative failures between model and measured values is good during validation phase. It is obvious that the testing time was too short to achieve the predicted final number of failures. According to the model prediction for the presented case, three failures could be expected after this period as the difference between predicted value for

 v_0 and the final number of measured failures from Table 7. In the presented case, it was decided that achieved reliability of three predicted future failures is good enough for the developed product. The graph for this is shown in Fig. 6.

Model and Measure Cumulative failures-Time for the System Testing



Fig. 6: Graph of Cumulative Failures (Comparison between measured and model)

In evaluating the system using black box testing, a total of six (6) errors were detected and using the model, two (2) more errors were uncovered; and because these two (2) errors were not corrected during the actual testing, we have a reliability of 0.75 (75%). With the result of these two (2) testing methods, it shows that the software is very reliable.

5. CONCLUSION

In this paper, we used the Musa's basic execution time model which was sufficient for reliability modelling of the eNCMS presented. This model was able to give predictive information (expected number of future failures) about the system. It is also possible to apply described model to other problems such as the optimal software release problem.

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