Swarm robots are a new approach in the robotic system. This idea of Swarm Robots is designed from the idea of small insects. Swarm robots can work co-ordinately and achieve its common goal. Self-organizing map (SOM)-based on the multi robots that have self-organizing criteria, Co-ordination and that can also be approached for dynamic environment. It can control number of robots and achieves different task locations randomly and gets its initial locations and directions.

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