Design and Comparative Analysis of SRAM with Performance Optimization using MTCMOS Technique for High Speed Computation

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ABSTRACT

SRAM is faster and more expensive and it is typically used for CPU cache. SRAMs are the fastest form of RAM available which does not need to be refreshed periodically. Here, 6T SRAM cell with O-ABB circuit is designed. On-chip adaptive body bias (O-ABB) circuit consists of standby leakage current (Iddq) sensor circuit, decision circuit and body bias control circuit which are used to compensate the effect of NBTI. Dynamic power is the power measured when circuit is in active mode. Here, Multi Threshold Complementary Metal Oxide Semiconductor (MTCMOS) technology is applied in the individual circuit of On-chip adaptive body bias to decrease the power. Low power MTCMOS methodology is applied in the proposed circuit which provides high performance and low power design. Design metrics such as Power, Delay and Power delay product are taken in to account. After applying MTCMOS technology, the power and the power delay product of the proposed circuit decreases when compared the existing circuit. All the circuits were designed using SYNOPSYS EDA tool and simulated in 28nm technology.

Keywords

CMOS, MTCMOS, Power, Delay, Adaptive body bias.

1. INTRODUCTION

Very large scale integration (VLSI) is the technique of generate an integrated circuit (IC) by combining thousands of transistors into a single chip. The microprocessor is a VLSI device [4]. Earlier than the beginning of VLSI technology the majority ICs had a limited set of functions they could execute. An electronic circuit may consist of a CPU, ROM, RAM and other glue logic. VLSI lets IC designers made to join all of these into single chip.

The insufficiency on power dissipation in moveable electronics applications such as smart phones and tablet computers have to be met by the VLSI chip designer even as still meeting the computational requirements[2].

While wireless devices are quickly making their way to the consumer electronics market, a key design limit for moveable process namely the total power consumption of the device must be addressed. Reducing the total power consumption in such systems is significant since it is advantageous to maximize the run time with minimum requirements on size, battery life and weight allocated to batteries. So the most important feature to consider while designing SoC for moveable devices is low power design [13].

Dynamic Power occurs when signals which undergo the CMOS circuits change their logic state. At this instant energy

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is drawn from the power supply to charge up the output node capacitance [5] in which charging up of the output capacitance causes transition from 0V to Vdd.

The Propagation delay is calculated between 50% of input transition to the corresponding 50% of output transition for any gate[20]. This is the time needed for a signal to propagate through a gate or net. It is the time takes for an event at the gate input to have an effect on the gate output for gates.

The fall time is the difference between the time when the signal crosses a high threshold to the time the low threshold whereas the difference between the time when the signal crosses a low threshold to the high threshold is said to be the rise time.

The power delay product or switching energy is the energy efficiency of a logic gate or logic family. The product of the power consumption (averaged over a switching event) times the input–output delay, or duration of the switching event [6]. It has the measurement of energy, and measures the energy consumed per switching event.

The paper is well organised as follows. In section 2, 6T SRAM cell are explained below. In section 3, On-chi adaptive body bias is explained. In section 4, the existing circuit design and in section 5, the proposed circuit design using MTCMOS is explained below. In section 6, the simulation result and analysis are discussed.

2. 6T SRAM CELL DESIGN

The 6T SRAM cell consist of 6 transistor, two pull up transistor (M4,M5), two pull down transistor (M3,M2) and two pass transistor (M0,M1). The gate of pass transistors is controlled by the word line inputs (wl1,wl). The bl and blb are connected to the cell so that the cell can be read out or write in from the bit lines whenever the word lines are high. When the word lines are off there is no reading or writing is performed by the cell, so that the cell will be in the hold state [9]. The power measured in this state is called static or leakage power dissipation. For successful writing in the cell there must be a write driver which allows the data to be written into the cell and monitor the presence of data. This write driver is simple a AND gate whose input are write enable and data. The schematic representation of SRAM cell is shown in the below fig 1.



Fig 1: 6T SRAM Cell

3. ON-CHIP ADAPTIVE BODY BIAS CIRCUIT

The O-ABB is used to compensate the parameter variations and improves the SRAM circuit yield regarding read current, hold SNM, read SNM, write margin, and word line write margin (WLWM)[1]. The O-ABB consists of standby leakage current (*Iddq*) sensor circuit, decision circuit, and body bias control circuit.

3.1 NBTI Sensor Circuit

A Linear and Sensitive On-chip NBTI sensor circuit is proposed. Here, M1 and M2 act as a resistor are self-drain biased (diode-connected) and in combination voltage divider. The output of this voltage divider section is flowing through the circuit under test (SRAM cell) which depends on standby leakage current Iddq. The output of the voltage divider is passed through a push-pull amplifier (M3 and M4) to improve the final output. With change in the Iddq, the proposed sensor gives the change in the output vout. If the sensor shows the negative resistance behavior, then the slope of the sensor is negative. Any change in Iddq, changes the value of vx which reflects the values of RM3 and RM4. As Iddq increases, the voltage drop (vx) across RM2 increases, which increases and decreases the value of RM3 and RM4 respectively [19]. This is because of increasing value of vx to turn ON the M4 and turn OFF the M3 [8]. The schematic representation of the NBTI Sensor circuit is shown in the fig. 2.



Fig 2: NBTI Sensor Circuit

3.2 Decision Circuit

Decision circuit consists of 2x1 mux, comparator, level shifter and sense amplifier. A multiplexer (or mux) is a device that selects one of several analog or digital input signals and forwards the selected input into a single line. Low power consumption can be achieved by sense amplifiers which are main part of CMOS memory. Parasitic capacitance is much higher if memory is of high density [5]. To achieve a faster memory and less power dissipation to design sense amplifiers as, increase in number of cells per bit line which will increase the parasitic capacitance. Minimize supply voltage lead to short amplifier reliability. Comparator is used to compare the output voltage of the NBTI (Vsensor) and the output voltage of the level shifter (Vref). A comparator is used to decide whether the SRAM cell is affected by NBTI or not. The block diagram of the decision circuit is shown in the fig 3.



Fig 3: Decision Circuit

3.3 VB Generator Circuit

The VB Generator circuit which is used to compensate the effect of NBTI in the test circuit. The O-ABB circuit consists of the decoder circuit and VB voltage control circuit. To generate different voltage levels diode-connected MOSFETs are connected in series which act as resistances in the decoder circuit. Several MOS devices can be connected in diodeconnected topology to provide an alternative to the precision resistor for generation of different voltages and elimination of large valued resistor because it is difficult to incorporate the large value of resistance in integrated circuits [15]. The sizing of transistors is adjusted in decoder circuit in such a manner it gives equal voltage drop across each diode-connected MOSFET. Depends on the output of the amplifier (VDec), each diode-connected MOSFET has some voltage drop. The VB voltage control circuit is implemented using pseudo NMOS logic where the gate of transistor Px is controlled by CLK. Px is the weak transistor so that the VB, PMOS voltage can be reduced by activating pull-down transistors [17]. The total number of NMOS transistors in pull-down network depends on the number of diode-connected MOSFETs in the decoder circuit. The activation/deactivation of NMOS transistors in pull-down networks depends on the voltage drop across the respective diode-connected MOSFET. The VB, PMOS voltage is controlled by the pull-down NMOS transistors [11]. The transistor sizing of all pull-down NMOS transistors are adjusted in such a manner which generates the VB,PMOS voltage according to the amount of threshold voltage shift due to temporal degradation and applied to the body terminal of PMOS in SRAM cell to counterbalance the threshold voltage of PMOS transistor which was affected by the NBTI. The schematic representation of the VB Generator circuit is shown in the fig. 4.



Fig 4: VB Generator Circuit

4. EXISTING CIRCUIT DESIGN

Negative bias temperature instability (NBTI) is a major reliability issue with the scaled devices at elevated temperature. The effect of NBTI increases with the time, and it increases the threshold voltage of PMOS. In this paper, an O-ABB circuit to compensate the degradation due to NBTI aging is presented. The O-ABB is used to compensate the parameter variations and improves the SRAM circuit yield regarding read current, hold SNM, read SNM, write margin, and WLWM. The O-ABB consists of standby leakage current (Iddg) sensor circuit, decision circuit, and body bias control circuit. Circuit level simulation for SRAM cell is performed for pre- and post-stress of ten years NBTI aging. The Proposed O-ABB reduces the effect of NBTI on the stability of SRAM cell [3]. The schematic representation of existing circuit.ie, SRAM with O-ABB circuit is shown in the below fig 5.



Fig 5: Schematic of existing SRAM with O-ABB circuit

5. PROPOSED CIRCUIT USING MTCMOS TECHNIQUE

MTCMOS is a variation of CMOS chip technology which has transistors with multiple threshold voltages (V_{th}) in order to optimize delay or power. The V_{th} of a MOSFET is the gate voltage where an inversion layer forms at the interface between the insulating layer (oxide) and the substrate (body) of the transistor. Low Vth devices switch faster, and are therefore helpful on critical delay paths to minimize clock periods [13]. The consequence is that low Vth devices have considerably higher static leakage power. High Vth devices are used on non-critical paths to reduce static leakage power without incurring a delay penalty. Typical high Vth devices decrease static leakage by 10 times compared with low Vth devices.One method of creating devices with multiple threshold voltages is to apply various bias voltages (Vb) to the base or bulk terminal of the transistors. Other methods involve adjusting the gate oxide thickness and dielectric constant (material type), or doping concentration in the channel region beneath the gate oxide [16].

A common method of fabricating multi-threshold CMOS involves just adding extra photolithography and ionimplantation step. For a given fabrication process, the Vth is adjusted by varying the concentration of doping atoms in the channel region beneath the gate oxide. In general, the concentration is adjusted by ion implantation method. For example, photolithography methods are applied to face all devices except the p-MOSFETs with photo resist [18]. Ion implantation is then finished, with ions of the chosen doping type penetrating the gate oxide in areas where no photo resist is present. The photo resist is then stripped. Photolithography methods are once more applied to cover all devices excluding the n-MOSFETs. Another implantation is then completed using a special doping type, with ions penetrating the gate oxide. The photo resist is stripped [4]. At some point during the consequent fabrication process, implanted ions are activated by annealing at an elevated temperature.

In principle, any number of threshold voltage transistors can be created. For CMOS having two threshold voltages, one extra photo masking and implantation step is necessary for each of p-MOSFET and n-MOSFET. For fabrication of normal, low, and high Vth CMOS, four additional steps are necessary relative to conventional single-Vth CMOS [14].

The most general implementation of MTCMOS for decreasing power makes use of sleep transistors. Logic is supplied by a virtual power rail. Low Vth devices are used in the logic where rapid switching speed is essential. High Vth devices connecting the power rails and virtual power rails are turned on in active mode, off in sleep mode [10]. High Vth devices are used as sleep transistors to decrease static leakage power.

The design of the power switch which turns on and off the power supply to the logic gates is necessary to low-voltage, high-speed circuit techniques such as MTCMOS. The schematic representation of proposed circuit.ie, SRAM with O-ABB circuit using MTCMOS is shown in the below fig 6.



Fig 6: Schematic of proposed SRAM with O-ABB circuit

6. SIMUATION RESULTS AND DISCUSSIONS

Here the SRAM cells were designed using SYNOPSYS tool in 28nm technology. The parameters measured are dynamic power, delay and power delay product. The parameter power delay product was calculated from measured values of power and delay. Parameters are defined as dynamic power measured when circuit is in active mode. Delay is the difference in time the output switches after application of input. Power delay product is the parameter is obtained by the product of power and delay value.

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Voltage in Volts	Existing Circuit	Proposed Circuit
1	5.86	1.3
0.9	2.41	535m
0.8	149m	33.1m
0.7	3.78m	840u
0.6	97.5u	21.4u

Table.1 Power Comparison of Existing vs Proposed Design

In table 1, the power of the existing and proposed Circuit is compared. For different supply voltages and input, the power dissipation value changes. Here the power of the proposed circuit is decreased by 77.80% when compared to the existing Circuit.

Table.2 Delay Comparison of Existing vs Proposed Design

Voltage in Volts	Existing Circuit	Proposed Circuit
1	6.9p	6.97p
0.9	8p	10.2p
0.8	11.1p	15.6р
0.7	14.1p	26.7p
0.6	18.2p	44.4p

In table 2, the delay of existing and the proposed circuit is compared. For different supply voltages and input, the delay value changes.

Table.3 Power Delay Product Comparison of Existing vs Proposed Design

Voltage in Volts	Existing Circuit	Proposed Circuit
1	40.434p	9.061p
0.9	19.28p	5457f
0.8	1653f	516.36f
0.7	53.298f	22.428f
0.6	1.774f	0.9501f

In table 3, the power delay product of existing and proposed circuit is compared. For different supply voltages and input, the power delay product value changes. Here the power delay product of the proposed circuit is decreased by 64% when compared to the existing circuit.

For NBTI Sensor circuit, we give the input as IDDQ (00001111) and the output as VOUT and the waveform is as shown in the fig 7.



Fig 7: Waveform of NBTI Sensor Circuit

For VB Generator circuit, we give the input as enb (10101010), clk (10101010), vdec (01010101) and the output as VB and the waveform is as shown in the fig 8.



Fig 8: Waveform of VB Generator Circuit

For Proposed design circuit, we give the input as bl (10101010), blb (0101010), ctrl (10100000), WL (11111111), FV (11111111), SE (10010110) and the output as Q and QB and the waveform is as shown in the fig 9.



Fig 9: Waveform of Proposed design Circuit

7. CONCLUSON AND FUTURE SCOPE

In this paper O-ABB circuit is connected with the SRAM cell. Here the parameters such as power, delay and the power delay product is calculated. The most important factor to consider while designing semiconductor IC for portable device is low power design. The scaling of CMOS technology in nanometer technology effectively reduces supply voltage and threshold voltage. Lowering of threshold voltages leads to an exponential increase in the sub-threshold leakage current. Overweening power dissipation in digital integrated circuits, not only affects their use in portable devices but also causes overheating, degrades performance, reduces chip life and functionality. In the modern high performance integrated circuits, more than 40% of the active mode power is dissipated due to the leakage current. Here, by using MTCMOS technology the power of the individual circuit is reduced. Therefore the total power of the circuit is reduced upto 77.8% and thereby the power delay product is decreased by 64.35%. In modern day processor power dissipation plays a major role because of the miniaturization of chip design. So this MTCMOS technique can be used in future where considerable reduction of power. SRAM is used as the primary caches in powerful microprocessors. The proposed SRAM cell can be used in the area of suitable low power and hign speed applications.

8. OBSERVATIONS FROM THE RESULT

From the result, it is known that by various parameter such as power, delay and power delay product were calculated. Dynamic power is the power measured when circuit is in active mode. Here the power is taken into consideration for NBTI Sensor, Mux, Comparator, Level Shifter, Amplifier and Vb Generator circuit. Here the power is decreased by 15.58%, 65.74%, 27.6%, 89.12%, 97.8% and 41.2% when compared to the existing circuit. Power delay product is the parameter that is obtained by the product of power and delay value. Similarly, the power delay product of the above listed each individual circuit is decreased by 45.9%, 23.09%, 19.5%, 98.04% after applying MTCMOS technology.

9. **REFERENCES**

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