Abstract
This paper aims at developing path traversal algorithm based on the co-ordinates of the axis for Firebird V robot. This algorithm does not require physical indications like markers, white lines and black lines for its path. These robots can be used in surveying pipes, small areas. Robot traces the path drawn by the user using GUI controller application. The Bluetooth module is used to establish communication between robot and computer.

References

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Index Terms

Computer Science
Algorithm

Keywords

Bluetooth Module    Traversal    Firebird V Robot    Gui