

# Public Road Transport Guiding System using Arduino Microcontroller

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## ABSTRACT

Majority of the public transport supportive system is not user friendly. An ambiguity on the available state of the transport bus may lead to poor performance of the supportive mechanism. . The advancement of technology enabled, to meet the requirements of the supportive mechanism. The bus is entering into the bus stand premises, the bus is located at the stop point, the bus is leaving out gate, next bus in a queue, such information will be displaced at the appropriate display point and an automatic announcement is added to the proposed work. 'ARDUINO' Micro controller is adopted to regulate the process. Three IR Sensors are inputted to Arduino controller. An RFID reader at the entrance gate of the bus stand will detect the entry level of the bus, and the gate controlling mechanism will verify the authorization of the bus to enter into the bus stand premises.

## Keywords

ARDUINO Micro controller, RFID Reader

## 1. INTRODUCTION

Road transport system will be powered by adopting the growing technology to make sense for the society. Monitoring the state of each platform manually may leads to inappropriate errors. Tracking of the bus on the platform manually is a tedious process. Supervise the process and display the state of each platform can be accomplished by means of Ardino microcontroller supported by the RFID and infrared Technology. Unauthorized vehicles will be restricted in the bus stand premises using the proposed RFID Technology. The proposed methodology was developed for implementation in real time application.

## 2. LITERATURE SURVEY

Mrs.Swati Chandurkar, Sneha Mugade, Sanjana Sinha, Megharani Misal, Pooja Borekar focused to install Global positioning system (GPS) on City buses to implement the real time passenger information system. The bus tracking at the control room is developed to meet the challenges of web based interface at the central control room, expected time of arrival at bus stops, mobile application to know the bus schedule [1].

Menon1, R. Sinha, D. Ediga, Prof. Subba Iyer proposed the implication of internet of things in bus transport system of Singapore. This paper also compared the developed application with the existing applications [2].

Aparna A. Surve, Rutuja P. Nahar, Gauri K. Somavanshi, Kranti Dive, proposed a methodology to Enhancing the Functionality of Bus Monitoring and Tracking System. The author focused to reduce the waiting time of the passengers by implementing the GPS system. the exact time and location of the bus is estimated with the proposed methodology. I2 T

algorithm is applied to determine the shortest path between the user and the nearest bus stop [3].

Sunil Praneel Narayan, Mansour H. Assaf, Shalvindra Krishneel Prasad, proposed automated vehicle identification system . Public vehicle location. System (PVLS) is proposed with the support of RFID readers and tags. Managing the RFID readers at various locations is the major contribution of the proposed work [4].

Gunjal Sunil N. , Joshi Ajinkya V. , Gosavi Swapnil C. , K.shirsagar, V.yanktesh B proposed a methodology using Global position system to estimate the expected time of arrival at the located places using internet [5].

Karan Punjabi, Pooja Bolaj, Pratibha Mantur, Sneha Wali proposed a methodology using GPS and Global position receiving system (GPRS) to implement the college bus locator using Via SMS using android application. Location based service is the focused aim of this work [6].

Swapnil Bhosale, Abhishek Aru, Tushar Jashav, Vikas Kalokhe, Santosh Sambare proposed a methodology to implement RFID based bus tracking system. The author focused on GSM modem and RFID reader. At 89 S 52 is used as superstation controller [7].

Komal Agarwal, Kimaya Dhaigude, Priyanka Kataria, Dipti Parakh proposed a methodology for Public Transportation Management System. The work focused on a black box equipped in a bus contains RFID reader and GSM. The communicated information between RFID reader and RFID tag will be sent to the base station using GSM Technology [8].

RohanKale proposed a methodology to implement Real Time Passenger Information System. This work focused to1. display the arrival time of the buses at all the bus stop locations, 2. Control room monitoring by adopting the web based control, 3. Expected time to reach the destination.[9].

## 3. HARDWARE COMPONENT DESCRIPTION

### 3.1 RFID Reader

EM 18 RFID Reader is equipped at the entrance gate of the bus stand. Each bus is housed with the RF ID identity tag. The information to be identified is stored in the microchip for transmission to the RFID reader using an antenna. The reader will communicate to the Arduino Microcontroller serially using the MAX 232 line driver to verify the threshold value. Fig 3.1 represents EM18 used as a RFID reader.



Fig.1 RFID Reader

### 3.2 IR sensor

An IR Sensor equipped at the exact location of the parking place to detect the bus. If the detection is true then the IR sensor will fed 5V signal to the Arduino microcontroller. A beep signal enables to transmit the command signal to the control room cause to display the present state of the bus.

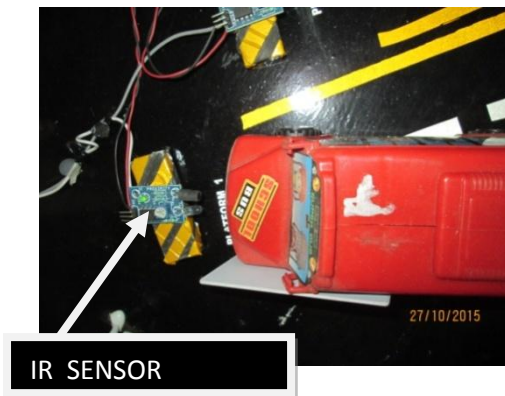


Fig.2 IR sensor detected when bus at platform

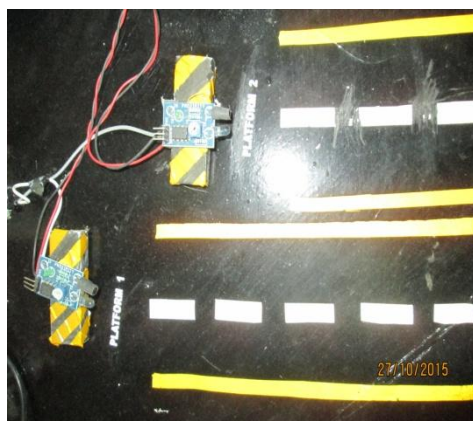


Fig.3 Two IR sensors at two platforms

### 3.3 Audio play back Board

APB 33A3 Audio play back board is used to address the public passengers. APB 33A3 housed with Eight Channels (M0 –M7). Each channel can hold the audio information maximum of 1.3 minutes. The total playback voice is ‘11’

minutes only. Jumper 5 (J5) used to select the channels. Keeping the jumper (J1) in record mode connect to the ground and on chip MIC used for recording the voice. The status LED 1 will be on for 1.3 minutes and it turns off after the duration is full. The public addressing speaker is connected to the jumper 4 (J4).



Fig.4 Audio play back circuit board

## 4. METHODOLOGY

- Initialize an address for Vijayawada rout bus
- Initialize an address for Khammam rout bus
- Initialize an address for Kothagudem rout bus
- Initialize the audio play back (APB) module for public addressing
- Initialize the Loop1 iteration count
- Initialize the Loop 2 iteration count
- Initialize the loop 3 iteration count
- Initialize the LCD display
- Initialize the Gate driving motors

### LOOP 1

- Read the RFID reader
- If
  - The pin goes high
  - Then decode the address
  - If
    - The address is for Vijayawada
    - Then display the message “Vijayawada bus is at the in gate”
    - Enable the APB module
    - Else if
      - The address is for Khammam
      - Then Display the message “Khammam Bus is at the in gate
      - Enable the APB module
      - Else if
        - The Address is for kothagudem
        - Then Display the message “Kothagudem bus is at the in gate”
        - Enable the APB module

Else  
Display the message “Bus is not available “  
Enable the APB module  
Decrement the loop 1 iteration count by 1  
Open the in gate  
Go to loop 2

### LOOP 2

Read the IR Sensor 1  
If the output line is high  
Then Display the message “Vijayawada bus is at platform”  
Enable the APB module  
Else if  
Read the IR sensor 2  
If the output line is high  
Then display “Khammam bus is at platform”  
Enable the APB module  
Else if  
Read the IR sensor 3  
If the Output line is high  
Then display “Kothagudem bus is at plat form”  
Enable the APB module  
Else  
Display “welcome to Sattupalli”  
Decrement the loop 2 Iteration count by 1  
Go to loop 3

### LOOP 3

Read the RFID reader at the Out gate  
If  
The pin goes high  
Then decode the address  
If  
The address is for Vijayawada  
Then display the message “Vijayawada bus is leaving the out gate”  
Enable the APB module  
Else if  
The address is for Khammam  
Then Display the message “Khammam Bus is leaving the out gate”  
Enable the APB module  
Else if  
The Address is for Kothagudem  
Then Display the message “Kothagudem bus is leaving the out gate”

Enable the APB module  
Else  
Decrement the loop 3 iteration count by 1  
Open the out gate  
Go to loop 1

## 5. RESULTS AND DISCUSSION

The experiments were conducted by keeping the RF ID tags to the Tested Bus and the RFID reader is positioned at the entrance gate of the bus stand. The output signals of the RFID reader is communicated to the Arduino micro controller serially using RS 232 serial communication protocol. PD’0’ pin of the Microcontroller is used to receive the signals from the RFID reader. The received signals will be analyzed to enable the output devices. L293D H-Bridge circuit is used to drive the motor assembly positioned at the input and output gate of the bus stand. The In gate will be opened only when an authorized address is detected at the gate level. The out gate is normally in closed state. The On state of the IR sensors positioned at the parking places cause to enable the display and announcement systems. Fig.5 and Fig.6 Represents the developed working model of the yerragunta bus stand. The controller represented in fig.6 is used to drive the gate to be open when an authorized bus detected by the RFID reader. The gate will be closed once the bus leaves the gate. Fig.11 represents the control room to regulate the position and movements of the bus. Fig.9 and Fig.10 represents the display status of the Vijayawada bus leaving the platform and Khammam Bus at the platform with audio announcement. After repeated testing of the developed model the applied EM-18 RFID reader responded favorably to the RFID tag housed with the bus entering into the stand. With the use of IR detectors the response time is improved with no delay while bus is entering towards the platform.



Fig.5 Yerragunta Bus Stand view



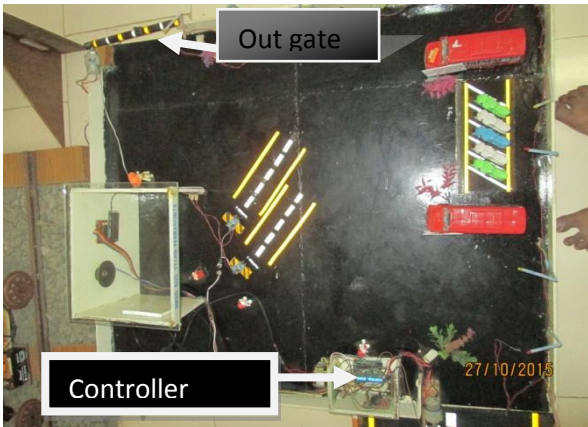


Fig.6 Developed working model



Fig.9 Bus leaving status



Fig.7 Bus Entering into the bus stand



Fig.10 Bus at platform



Fig.8 Bus detected , gate open state

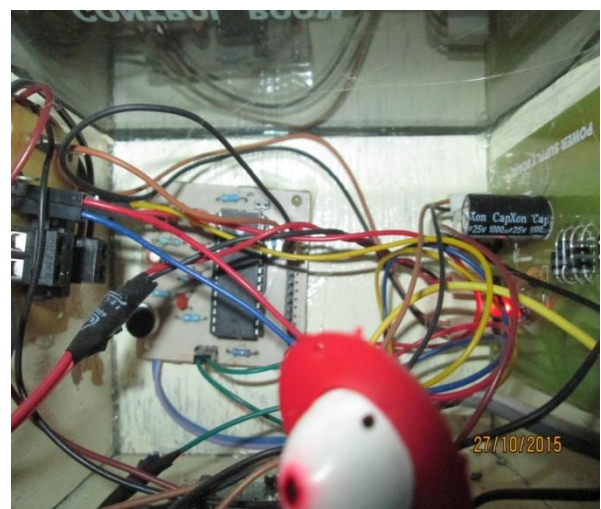


Fig.11 Control room

## 6. CONCLUSION

The proposed methodology was implemented in our in house research department. Majority of the researchers focused on the prediction mechanism of the bus arrival and its current location. This work focused on bus station management system. The status of the bus at the platform may curtail the

waiting time of the passengers. Arduino micro controller reached the desired expectations of the work. The regulatory mechanism at the in and out gate may enable the security system of the passengers by restricting the unauthorized entry.

In future this work may be further extended with Internet of things by incorporating the web based applications. So the travel passengers can observe the state of the bus at their desired location points.

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