# An Algorithm for Radial Basis Function Neural Networks 

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#### Abstract

A radial basis function ( RBF ) neural network depends mainly upon an adequate choice of the number and positions of its basis function centers. In this paper we have proposed an algorithm for RBF neural network and the results may be reduced for artificial neural networks as particular cases.


## Categories and Subject Descriptors

I.2.0 Artificial Intelligence

## General Terms

Neural Networks, Radial Basis Function, Algorithm

## Key Words

Radial Basis Function, Neural Networks, Algorithm

## 1. INTRODUCTION

The radial basis function neural networks are powerful function approximators for multivariate nonlinear continuous mappings. They have a simple architecture and the learning algorithm corresponds to the solution of a linear regression problem. The RBF network behavior strongly depends upon the number and the position of the basis functions at the hidden layer. Traditional method of determining the centers are randomly choose input vectors from the training data set or to obtain vectors from unsupervised clustering algorithms applied to input data or vectors obtain through a supervised learning scheme. In this paper we have proposed a new algorithm for RBF neural network and the results may be reduced for artificial neural networks as particular cases.

$$
\begin{aligned}
& \text { Let } x_{1}, x_{2}, \ldots, x_{r} \text { is a set of points and } \\
& c_{i} ; i=1,2, \ldots, r \text { be the set of centers, then } \\
& \left\|x_{i}-c_{i}\right\| \quad ; \quad \mathrm{i}=1,2, \ldots, \mathrm{r}
\end{aligned}
$$

be the radial vectors in Euclidean sense. If the corresponding weights are

$$
w_{i} ; i=1, \ldots, r
$$

the radial strength of $x_{i}$ will be

$$
w_{i \|} x_{i}-c_{i}{ }_{\|} ; \mathrm{i}=1,2, \ldots, \mathrm{r}
$$

Then the combined probabilistic strength of type $x_{i}$ will be

$$
\frac{\left\{w_{i}\left\|x_{i}-c_{i}\right\|\right\}^{m_{i}}}{m_{i}!}
$$

for $m$ external input lines for $n$ units of RBF neural network.

If we choose an activation function

$$
f\left(\sum_{i=1}^{r} m_{i}\right)
$$

The system output $y$ for first stage of network for the weight vector
$\mathrm{w}=\left(w_{1}, w_{2}, \ldots, w_{r}\right) ;\left(0 \leq w_{i} \leq 1\right)$ may be taken as

$$
f\left(\sum_{i=1}^{r} m_{i}\right) \mathrm{X}
$$



Similarly for second stage output

$$
y_{1}, \ldots, y_{s}
$$

We would have


Then for total output $Z$ of multilayer RBF neural network, we may adapt an unified activation function

$$
h\left(\sum_{i=1}^{r} m_{i}+\sum_{j=1}^{s} n_{j}\right)
$$

and therefore ( Because in case of indefinite large numbers the probabilistic models are best suited for infinity ).

$$
\begin{aligned}
& \mathbf{Z}=\sum_{m_{1}, \ldots, m_{r}=0}^{\infty} \sum_{n_{1}, \ldots, n_{j}=0}^{\infty} h\left(\sum_{i=1}^{r} m_{i}+\sum_{j=1}^{s} n_{j}\right) \\
& f\left(\sum_{i=1}^{r} m_{i}\right) g\left(\sum_{j=1}^{s} n_{j}\right) \\
& \int_{i=1}^{r} \frac{\left\{w_{i}\left\|x_{i}-c_{i}\right\|\right\}^{m_{i}}}{m_{i}!} \\
& \sum_{j=1}^{s} \frac{\left\{w_{j}^{\prime}\left\|y_{j}-c_{j}\right\|\right)^{n_{j}}}{n_{j}^{!}!}
\end{aligned}
$$

$$
\frac{\left\{\sum_{i=1}^{r} w_{i}\left\|x_{i}-c_{i}\right\|\right\}^{m}}{m!}
$$

$$
\begin{equation*}
\frac{\left\{\sum_{j=1}^{s} w_{j}^{\prime}\left\|y_{j}-c_{j}\right\|\right\}^{n}}{n!} \ldots \tag{1}
\end{equation*}
$$

by using identity [ 9]

$$
\begin{aligned}
& \sum_{m_{1}, m_{2}, \ldots m_{r}=0}^{\infty} \sum_{n, n, \ldots n_{s}=0}^{\infty} f\left(\sum_{i=1}^{r} m_{i}+\sum_{j=1}^{s} n_{j}\right) \\
& g\left(\sum_{i=1}^{r} m_{i}\right) h\left(\sum_{j=1}^{s} n_{j}\right)_{i=1}^{m_{i}!} \frac{x_{i}^{m_{i i}}}{m_{j=1}^{s} \frac{y_{j}{ }^{n_{j}}}{n_{j}!}} \\
& =\sum_{m, n=0}^{\infty} \mathrm{f}(\mathrm{~m}+\mathrm{n}) \mathrm{g}(\mathrm{~m}) \mathrm{h}(\mathrm{n}) \\
& \\
& \frac{\left(\sum_{i=1}^{r} x_{i}\right)^{m}}{m!} \frac{\left(\sum_{j=1}^{s} y_{j}\right)^{n}}{n!} .
\end{aligned}
$$

In case of symmetrical layers $\mathrm{h}(\mathrm{m}+\mathrm{n})$ may be taken as constant, say k. Also a group of neurons are similar in structure, the $f(m)$ and $g(n)$ in (1) may be taken as modular parameters $\lambda^{m}$ and $\mu^{n}$ say. So we have

$$
\begin{array}{r}
\mathbf{Z}=\mathbf{k} \sum_{m, n=0}^{\infty} \frac{\left\{\lambda \sum_{i=1}^{r} w_{i}\left\|x_{i}-c_{i}\right\|\right\}^{m}}{m!} \\
\frac{\left\{\mu \sum_{j=1}^{s} w_{j}^{\prime}\left\|y_{j}-c_{j}\right\|\right\}^{n}}{n!}
\end{array}
$$

$$
=\mathbf{k}
$$

$$
e^{\lambda \sum_{i=1}^{r} w_{i}\left\|x_{i}-c_{i}\right\|+\mu \sum_{j=1}^{s} w_{j}^{\prime}\left\|y_{j}-c_{j}\right\|}
$$

Or
$\mathbf{Z} \alpha$

$$
\begin{equation*}
e^{\lambda \sum_{i=1}^{r} w_{i}\left\|x_{i}-c_{i}\right\|+\mu \sum_{j=1}^{s} w_{j}^{\prime}\left\|y_{j}-c_{j}\right\|} \tag{2}
\end{equation*}
$$

i.e. the RBF neural network output is directly proportional to exponentially weighted sum of inputs and middle stage outcomes taken radially along with constraints $\lambda$ and $\mu$ which may be suitably defined as per network configuration.

Particularly when we choose
$\mu=0$ in (2), we have $(\mathrm{Z} \rightarrow \mathrm{Y})$
$\mathbf{Y} \quad \alpha \quad e^{\lambda \sum_{i=1}^{r} w_{i}\left\|x_{i}-c_{i}\right\|}$.
Or for $c_{i}=0$
$\begin{array}{cccc} & & & e^{\lambda \sum_{i=1}^{r} w_{i} x_{i}} \\ & \alpha & e^{\lambda W X} & \ldots \text { (4) } \\ & & \\ & \text { where } \mathrm{WX}=\sum_{i=1}^{r} w_{i} x_{i}\end{array}$
a result proposed by author [10] for artificial neural network.

## 2. CONCLUSION

In this paper we have proposed an algorithm for radial basis neural networks for the lack of availability of proper algorithm in the discipline. The further work is being carried out and may bring some fruitful results in near future.

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