A ZigBee based collision avoidance system for railways has been proposed in this paper. The Train Anti-Collision System (TACS) has four sub centers namely, Train Subsystem, Station/Control Center Subsystem, Signalling Post Subsystem and Level Crossing Subsystem. A safe distance of 1 Km has been given for braking between the trains in case of collision distance. Based on the studies, it has been observed that even for two trains travelling at 120kmph, the safe distance after automatic braking under normal conditions has been estimated to be 920m. All subsystems have been designed and simulated using Proteus electronic simulation package and implemented. It is expected that if this system is
implemented, train collisions can be avoided in the future

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Index Terms

Computer Science  Hpc Applications

Keywords

Train Collision Avoidance  Proteus  Electronic System Design  Zigbee